

Total Station Survey Monitoring Through an Observation Window: A Systematic Error Correction to Remove the Effects of Glass Properties

Thomas B. Afeni¹ and Frederick T. Cawood¹

¹School of Mining Engineering, Faculty of Engineering and the Built Environment, University of the Witwatersrand, Johannesburg, South Africa.

Email: olubusuyiafeni@gmail.com; frederick.cawood@wits.ac.za

<http://dx.doi.org/10.4314/sajg.v5i2.3>

Abstract

Total stations are used extensively for taking geodetic and engineering survey measurements. These measurements are made possible by accurate observation of targeted points. One example is deformation surveys, slope stability monitoring, in mines. Continuous monitoring necessitates sheltering or housing the instrument to protect it against harsh weather conditions that are characteristic of mining environments. Previous studies carried out by Afeni and Cawood (2012) revealed that the properties of the glass material matters when using a total station to take observations through a glass window of a structure that houses the total station at a mine. This study briefly discusses total station survey monitoring and developed systematic error correction formula to reduce the effect of glass properties, such as thickness and colour, on distance measurements through a shelter window glass in a surface mine environment. Each developed formula is combined with the atmospheric corrections formula given by Leica Geosystem, who is the manufacturer of the total station used in this research, to form a combined atmospheric and glass correction formula. The formula performed well when tested on two sets of observations.

1. Introduction

Survey monitoring, be it slope monitoring or structural monitoring for movement, is done to detect movement that could lead to failure and to allow for sufficient warning to successfully evacuate the area or structure. Wyllie and Mah (2004) declared that, “because of the unpredictability of slope behaviour, movement monitoring programmes can be of value in managing slope hazards, and they provide information that is useful for the design of

remedial work". Slope movement is most common in open-pit mines, and many mines continue to operate safely for years with moving slopes that are carefully monitored to give warning of deteriorating stability conditions. The authors also described other human activities that can be detrimental to slope stability apart from open pit-mines, namely excavations of the base, and changing the ground water conditions by dam filling or irrigation. Total station monitoring survey techniques are common practice in many open-pit mines, in addition to other geodetic and geotechnical instrumentation. It has become the norm to use robotic total stations in a fully and automated way as part of the monitoring systems in mines (Duffy *et al.*, 2001; Leung, 2001).

The use of total station surveying instruments for monitoring structures' movement with good results were reported by many authors including Radovanovic and Teskey (2001), Hill and Sippel (2002), Kuhlmann and Glaser (2002), Zahariadis and Tsakiri (2006), as well as Lange and Kippelen (2008). Continuous monitoring, as an important operation in an open-pit mine to ensure the safety and stability of the mine highwall, was described by Palazzo *et al.*, (2006).

Since continuous slope monitoring with a total station requires the machine to be left in the field, this necessitates housing the instrument inside an observation house, or office, as the case may be. Slope monitoring is always carried out through the window of such an observation house. The window is usually covered with glass material. The properties of the window glass, such as thickness and colour, are not always taken into consideration during the selection, installation and actual monitoring process. Even if this impact may be an additive constant, its magnitude needs to be known and adequately catered for during the analysis of the survey monitoring data.

Systematic errors are not revealed by taking the same measurement again with the same instruments or method, such as taking total station distance measurements through an observation window glass. Taylor (1999) expressed that constant systematic errors are very difficult to deal with because their effects are only observable if they can be removed. Such an error cannot be removed by repeating measurements or averaging large numbers of results. The only way to check adequately for systematic error is to re-measure the quantity by an entirely different method, such as taking total station distance measurements without an observation window glass. It must be ensured that measurements are as accurate as required by removing the effects of all factors that, if neglected, would result in significant error. The

error caused by some factors can be eliminated with the correct observing procedure, and others can be countered by applying appropriate corrections (Bannister *et al*, 1998).

This study examined the likely impact of the glass properties, namely thickness and colour, on distances measured through it with a total station and provides a possible way of mitigating the impact.

2. Materials and Method

The research was carried out to isolate atmospheric corrections formula from glass properties, such as thickness and colour impact on distances measured with total station. This case study examines the likely impact of such observation window glass properties on distance measurement and developed systematic error correction formulae to remove or reduce such impact. A new total station – TCR 1201 – was procured due to its high sensitivity and accuracy specifications by the school of Mining Engineering, University of the Witwatersrand, Johannesburg for a PhD research project on likely impacts of atmospheric variation when taking observations through a window glass on the accuracy of data generated using total station surveying instruments. The school also procured five (5) clear float glass panes of different thickness, namely 2mm, 3mm, 4mm, 5mm and 6.38mm respectively, and two (2) tinted 3.0mm glass panes that could easily be exchanged in a special window frame as shown in Figure 1 below:

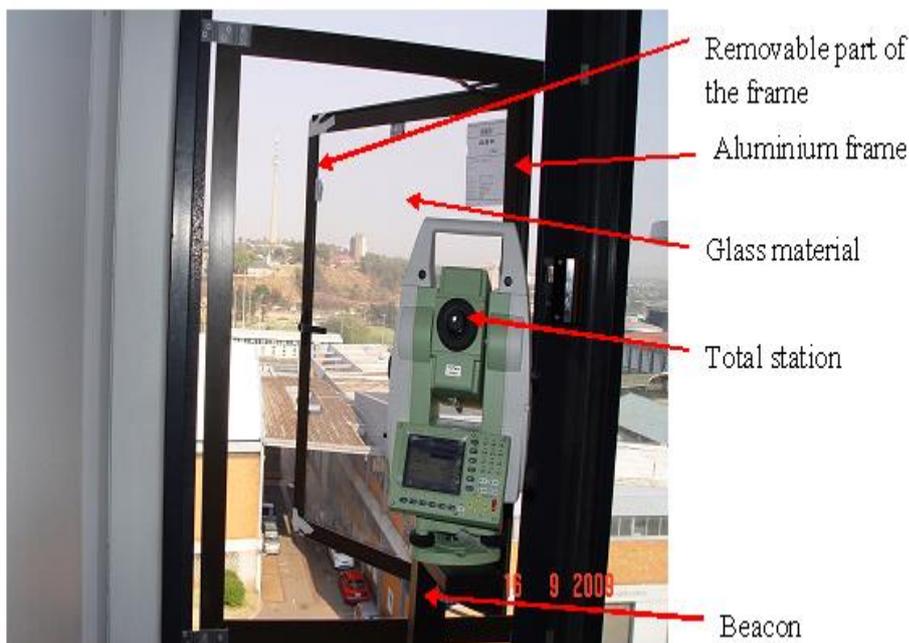


Figure 1: Instrument station set-up showing window frame, total station and beacon

The detail of materials and methods used to establish the importance of the impact of the glass properties, with regards to thickness and colour on distance measurements through instrument shelter window glass was explained by Afeni and Cawood (2012). The paper established that glass properties have an impact on the measured distances. It also established that the total station manufacturer-proposed atmospheric correction formulae work perfectly to cater for the effects of atmospheric variations on distances measured without glass. The formulae do not in any way remove or reduce the impact caused by the glass material on the distance measurements, because the formulae were not developed for glass impact correction. However, the authors noted that the glass material has little or no impact on vertical distance (VD) measurements and that the impact caused by 2.0mm and 3.0mm glass on horizontal distance (HD) measurements were within the accuracy limits of 1mm + 1.5 ppm, when using IR mode, as specified in the instrument manual regardless of different angles intersecting the glass (i.e. when the glass is at different angles to the line-of-sight of the total station). The data generated in Afeni and Cawood (2012) were subjected to linear regression to develop a model for removing the impact caused by the glass properties, such as glass thickness above 3.0mm and glass colour – light and dark tinted 3.0mm glass, on HD measurements with total station.

2.1 Development of Systematic Error Correction Formulae to Cater for the Impact of Glass Properties

The least squares procedure for fitting a line through a set of ‘n’ data points is to ensure that the differences between the observed values and corresponding points on the fitted line is “small” in a overall sense. According to Wackerly *et al.*, (2008), a convenient way to accomplish this, and one that yields estimators with good properties, is to minimise the sum of squares of the vertical deviations from the fitted line, as shown in Figure 2 below:

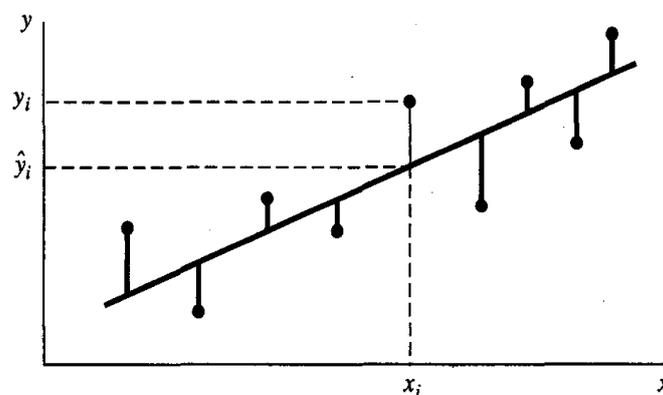


Figure 2: Fitting a straight line through a set of data points (Source: Wackerly *et al.*, 2008)

Thus, if:

$$\hat{y}_i = b_0 + b_1 \hat{x}_i \quad [1]$$

Where:

\hat{y} is the predicted value of the i th y value (when $x = x_i$), then the deviation, also known as error, of the observed value y_i from $\hat{y}_i = b_0 + b_1 \hat{x}_i$ is the difference $y_i - \hat{y}_i$ and the sum of squares of deviation, also called sum of squares for error, to be minimised is:

$$SSD = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \sum_{i=1}^n [y_i - (\hat{b}_0 + \hat{b}_1 x_i)]^2 \quad [2]$$

To find the values of \hat{b}_0 and \hat{b}_1 , which minimise SSD in equation 2; differentiate equation 2 with respect to \hat{b}_0 and \hat{b}_1 and set the results equal to 0:

$$\frac{\partial SSD}{\partial b_0} = \frac{\left\{ \sum_{i=1}^n [y_i - (\hat{b}_0 + \hat{b}_1 x_i)]^2 \right\}}{\partial b_0} = -\sum_{i=1}^n 2[y_i - (\hat{b}_0 + \hat{b}_1 x_i)] = -2 \sum_{i=1}^n (y_i - \hat{b}_0 - \hat{b}_1 x_i) = 0 \quad [3]$$

$$\frac{\partial SSD}{\partial b_1} = \frac{\left\{ \sum_{i=1}^n [y_i - (\hat{b}_0 + \hat{b}_1 x_i)]^2 \right\}}{\partial b_1} = -\sum_{i=1}^n 2[y_i - (\hat{b}_0 + \hat{b}_1 x_i)]x_i = -2 \sum_{i=1}^n (y_i - \hat{b}_0 - \hat{b}_1 x_i)x_i = 0 \quad [4]$$

Equations 3 and 4 above are called the least squares equations for estimating the parameters of a line. The least squares equations are linear in \hat{b}_0 and \hat{b}_1 , hence they can be solved simultaneously. By solving Equations 3 and 4 simultaneously (Rencher and Schaalje, 2007), we have:

$$\hat{b}_1 = \frac{\sum_{i=1}^n x_i y_i - n\bar{y}\bar{x}}{\sum_{i=1}^n x_i^2 - n\bar{x}^2} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{\sum_{i=1}^n x_i y_i - n\bar{y}\bar{x}}{\sum_{i=1}^n x_i^2 - n\bar{x}^2} \quad [5]$$

$$\hat{b}_0 = \bar{y} - \hat{b}_1 \bar{x} \quad [6]$$

where:

x_i is glass thickness (mm) or glass colour (% tint);

y_i is glass impact (m);

n is number of observation;

\bar{x} is mean of x_i , and

\bar{y} is mean of y_i .

In order to generate the regression equation, the average daily Horizontal Distance (HD) readings to the prism when testing glass thickness impact, as shown in Table 1, and the average daily HD readings to prism when testing glass colour impact, as shown in Table 2, were reduced to average daily HD readings per three days, as shown in Tables 3 and 4. Since the impact of the angular variations on the HD readings were negligible and still within the accuracy limits in all the glass properties and glass angles or position tested as established in Afeni and Cawood (2012). Therefore, all the HD readings were averaged without minding the glass angles. The HD readings without glass are kept constant as shown in Tables 5 and 6. Tables 5 and 6 show the average changes in HD readings per 3 days.

Table 1: Average daily HD readings to prism

Date	Glass thickness (mm)	HD to prism without glass	HD to prism with glass @ 45°	HD to prism with glass @ 60°	HD to prism with glass @ 90°
2009/10/06	2.00	626.5415	626.5425	626.5428	626.5427
2009/10/07	2.00	626.5410	626.5419	626.5420	626.5419
2009/10/08	2.00	626.5413	626.5424	626.5425	626.5423
2009/10/09	3.00	626.5410	626.5424	626.5427	626.5425
2009/10/10	3.00	626.5410	626.5428	626.5428	626.5429
2009/10/11	3.00	626.5411	626.5427	626.5429	626.5429
2009/10/12	4.00	626.5415	626.5439	626.5438	626.5436
2009/10/13	4.00	626.5416	626.5439	626.5438	626.5437
2009/10/14	4.00	626.5417	626.5441	626.5440	626.5438
2009/10/15	5.00	626.5413	626.5448	626.5444	626.5442
2009/10/16	5.00	626.5413	626.5447	626.5444	626.5442
2009/10/17	5.00	626.5416	626.5453	626.5451	626.5449
2009/10/18	6.38	626.5417	626.5457	626.5451	626.5450
2009/10/19	6.38	626.5420	626.5460	626.5455	626.5454
2009/10/20	6.38	626.5419	626.5461	626.5452	626.5452

Table 2: Average daily HD readings to prism

Date	3.0mm Glass colour (tinted)	Ave HD to prism without glass	Ave HD to prism with glass @ 30°	Ave HD to prism with glass @ 45°	Ave HD to prism with glass @ 60°	Ave HD to prism with glass @ 90°
2010/05/06	Dark	626.5417	626.5449	626.5451	626.5444	626.5441
2010/05/07	Dark	626.5417	626.5447	626.5448	626.5443	626.5437
2010/05/08	Dark	626.5418	626.5448	626.5451	626.5444	626.5441
2010/05/09	Light	626.5417	626.5444	626.5441	626.5443	626.5440
2010/05/10	Light	626.5415	626.5442	626.5438	626.5440	626.5438
2010/05/11	Light	626.5416	626.5441	626.5442	626.5443	626.5441
2010/05/12	Non	626.5417	626.5434	626.5433	626.5435	626.5434
2010/05/13	Non	626.5416	626.5434	626.5433	626.5435	626.5432
2010/05/14	Non	626.5416	626.5432	626.5433	626.5433	626.5432

Table 3: Average daily HD readings per 3 days - Glass thickness

Glass thickness (mm)	Average HD without glass	Average HD with glass	Difference (glass impact)
2	626.5414	626.5424	0.0010
3	626.5414	626.5431	0.0017
4	626.5414	626.5438	0.0024
5	626.5414	626.5447	0.0033
6.38	626.5414	626.5455	0.0041

Table 4: Average daily HD readings per 3 days - Glass colour

Glass colour	Glass thickness (mm)	Average HD without glass	Average HD with glass	Difference (glass colour impact)
None tinted (0%)	3.00	626.5416	626.5433	0.0017
Light tinted (5%)	3.00	626.5416	626.5441	0.0025
Dark tinted (50%)	3.00	626.5416	626.5445	0.0029

Table 5: Average change in HD per glass thickness

Glass thickness	Without glass	With glass (glass thickness impact)
2	0	0.0010
3	0	0.0017
4	0	0.0024
5	0	0.0033
6.38	0	0.0041

Table 6: Average change in HD per glass colour

Glass colour	Without glass	With glass (glass colour impact)
Non-tinted	0	0.0017
Light-tinted (5% tint)	0	0.0025
Dark-tinted (50% tint)	0	0.0029

Tables 5 and 6 above are used to prepare tables for least squares regression model, as shown in Tables 7 and 8.

Table 7: Average change in HD per glass thickness for least squares regression model

S/No	x_i (Glass thickness, mm)	y_i (Glass impact, m)	$x_i y_i$	x_i^2
1	2	0.0010	0.0020	4.000
2	3	0.0017	0.0051	9.000
3	4	0.0024	0.0096	16.000
4	5	0.0033	0.0165	25.000
5	6.38	0.0041	0.02616	40.704
Sum	20.38000	0.0125	0.05936	94.704
Mean	4.076	0.0025		

Table 8: Average change in HD per glass tint level or colour for least squares regression model

S/No	x_i (Glass colour, i.e. % tint level)	y_i (Glass impact, m)	$x_i y_i$	x_i^2
1	0	0.0017	0.000	0
2	5	0.0025	0.0125	25
3	50	0.0029	0.1450	2500
Sum	55	0.0071	0.1575	2525
Mean	27.5	0.0024		

Use Table 7 to substitute for values of parameters in Equations 5 and 6:

$$\hat{b}_1 = \frac{\sum_{i=1}^n x_i y_i - n \bar{y} \bar{x}}{\sum_{i=1}^n x_i^2 - n \bar{x}^2} = \frac{0.05936 - 5(4.076 \times 0.00250)}{94.704 - 5(4.076)^2} = 0.00072$$

$$\hat{b}_0 = \bar{y} - \hat{b}_1 \bar{x} = 0.0025 - 0.00072(4.076) = -0.0004$$

$$\hat{y} = -0.0004 + 0.00072 x$$

$$\hat{y}_{gtc} = 0.0007 x - 0.0004 \dots \dots \dots [7]$$

where:

\hat{y}_{gtc} is the error caused by the glass thickness or glass thickness impact formula. The subscript ‘gtc’ stands for glass thickness correction:

x is the glass thickness in mm.

Therefore, the combined formula, namely atmospheric and glass thickness corrections will be:

$$\Delta D_1 = \left[283.05 - \frac{79.7489 P}{(273.15 + t)} + \frac{11.27 e}{(273.15 + t)} \right] \cdot 10^{-6} d' - [0.0007 x - 0.0004] \dots \dots \dots [8]$$

Equation 8 above can be expressed as follows:

$$k' = a \cdot 10^{-6} d' - \hat{y}_{gtc} \dots \dots \dots [9]$$

where:

k' is the correction factor for atmospheric variation and glass thickness effect;

$a \cdot 10^{-6}$ is the atmospheric variation correction formula;

d' is the measured distance as it appears on the total station digital screen; and

\hat{y}_{gtc} is the glass thickness impact formula.

Equation 7 is the model for removing the impact of glass thickness, 4.0mm and above, on HD readings when using a total station surveying instrument.

Using the same procedure, Table 6 yields:

$$\hat{b}_1 = \frac{\sum_{i=1}^n x_i y_i - n\bar{y}\bar{x}}{\sum_{i=1}^n x_i^2 - n\bar{x}^2} = \frac{0.1575 - 2(27.5 \times 0.0024)}{2525 - 2(27.5)^2} = 2Exp^{-5}$$

$$\hat{b}_0 = \bar{y} - \hat{b}_1\bar{x} = 0.0024 - 2E^{-5}(27.5) = -0.0020$$

$$\hat{y}_{gcc} = 2Exp^{-5}x' + 0.0020 \dots\dots\dots[10]$$

where:

\hat{y}_{gcc} is the error caused by the glass colour, m. The subscript “gcc” stands for glass colour correction; and

x' is the tint level or colour of the glass (%).

Therefore, the combined formula for both atmospheric and glass colour corrections will be:

$$\Delta D_2 = \left[283.05 - \frac{79.7489 P}{(273.15 + t)} + \frac{11.27 e}{(273.15 + t)} \right] \cdot 10^{-6} d' - [2Exp^{-5}x' + 0.0020] \dots\dots\dots[11]$$

Equation 11 above can be expressed as follows:

$$k'' = a \cdot 10^{-6} d' - \hat{y}_{gcc} \dots\dots\dots[12]$$

where:

k'' is the correction factor for atmospheric variation and glass colour effect;

$a \cdot 10^{-6}$ is the atmospheric variation correction formula;

d' is the measured distance as it appears on the total station digital screen; and

\hat{y}_{gcc} is the glass colour impact formula.

2.2 Comparison of the Regression Model Developed with the Physical Model

The result of the comparison of the regression model developed for glass thickness impact correction with the physical model is presented in appendix A.

2.3 Observation/Distance Measurement to Test the Model

In order to test the effectiveness of the systematic error correction formulae developed in the field, two new target stations were chosen to resemble a surface mine environment. The line-of-sight to the two stations passed over a roofing sheet for varying heat generation, a

football pitch for dust generation and a highway for car exhaust and dust generation in order to simulate a mine environment. Dust, smoke and varying temperature reading are characteristics of mine environments and all these factors were experienced in these new target stations. The first set of HD readings was taken when the target was placed about 468m horizontal distance before the target/prism station used to develop the model. The target was later placed beyond the target station used to develop the model, approximately 697m in length, to generate the second set of HD readings for validation purposes. During the first set of HD measurements for the model tests, each glass material, namely glass thickness of 4.0mm, 5.0mm and 6.38mm for the thickness test, and light and dark-tinted glass were used for the glass colour test, was used for two days from 6.00 am to 6.00 pm daily. The data acquired was corrected for prism constant, scale factor and atmospheric corrections. The targets were later moved to the second station, and each glass material was used for only one day as opposed to two days in the first target station. The data acquired was also corrected for prism constant, scale factor and atmospheric corrections. The data was subjected to further analysis and tests to remove the glass impacts on the acquired HD readings.

3. Results and Discussions

3.1 Result and Discussions for Glass Thickness

The result of the data analysis when monitoring to the Leica circular prism at the first target position during the glass-thickness model test is presented in Figure 3 below. The graph shows the average daily HD measurements corrected for prism constant, scale factor and atmospheric corrections, but not corrected for glass impact. The corresponding result after all corrections, such as the prism constant, scale factor, atmospheric and glass corrections, is presented in Figure 4.

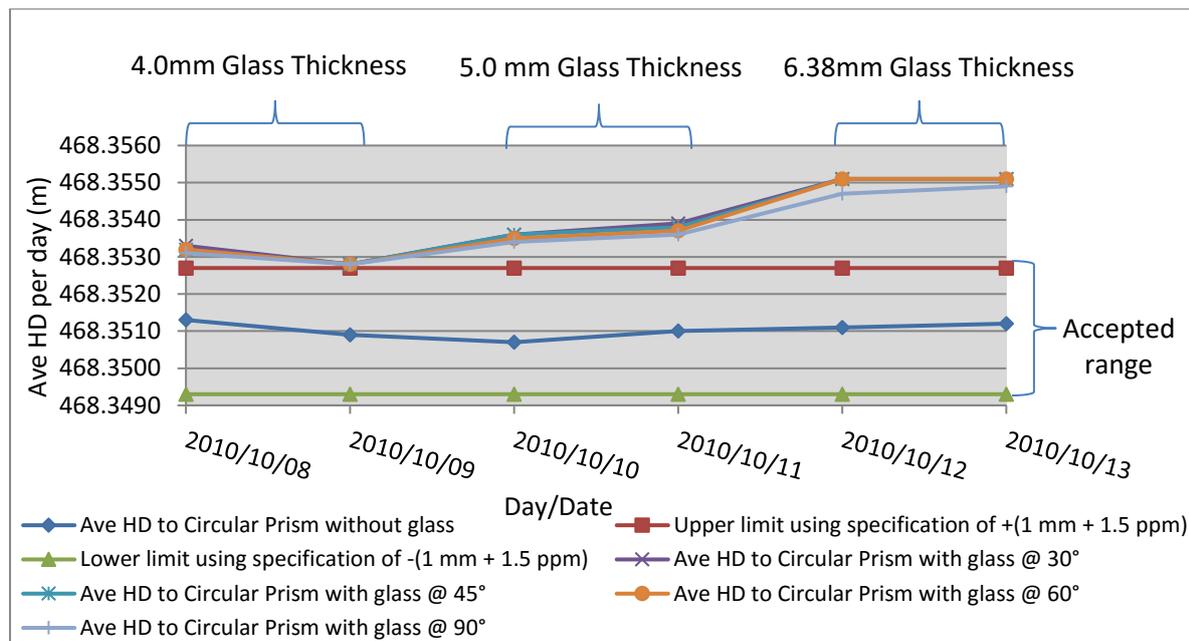


Figure 3: Average HDs to circular prism corrected for prism constant, scale factor and atmospheric corrections, but not corrected for glass thickness impact, as seen in the first target station

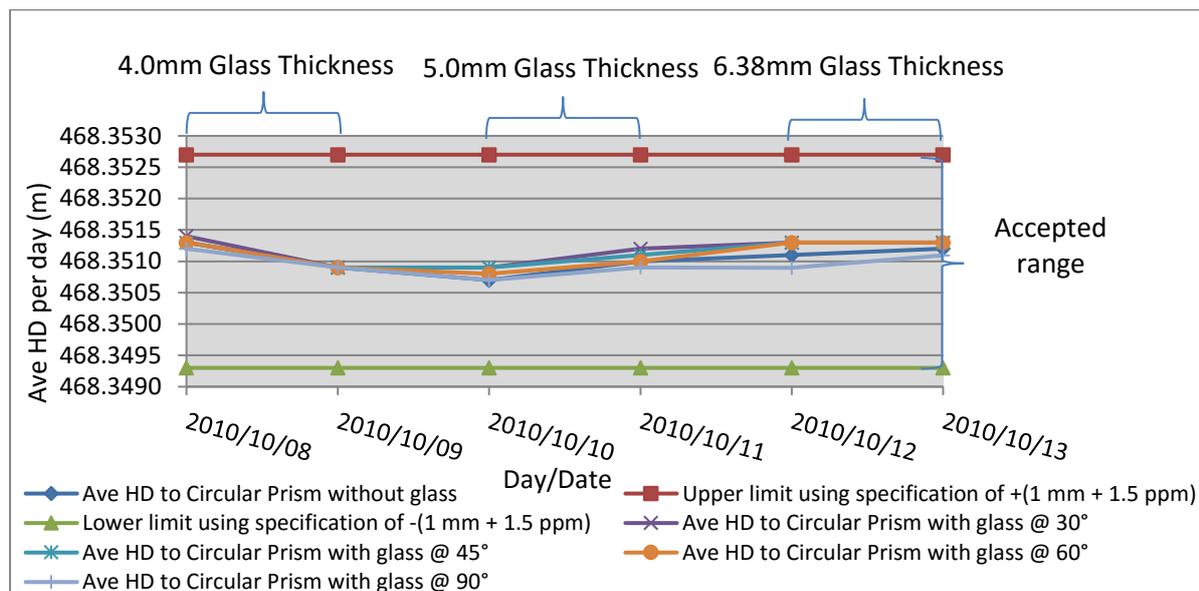


Figure 4: Average HDs to circular prism corrected for prism constant, scale factor, atmospheric and glass thickness, as seen in the first target station

In Figure 3 above, the impact ranged between 1.8mm and 2.0mm when a 4.0mm glass was used. It ranged between 2.6mm and 2.9mm when a 5.0mm glass was used, while a 6.38mm glass caused 3.6mm and 4.0mm impacts. The situation changed after applying the glass-thickness correction formula, as demonstrated in Figure 4. The impact range created by a

4.0mm glass was reduced to -0.1mm and 0.1mm, a 5.0mm glass impact range changed to -0.1mm and 0.2mm, while a 6.38mm glass impact changed to -0.1mm and 0.2mm after applying the glass-thickness correction formula to the HDs readings.

The results of the data analysis when monitoring to the Leica circular prism at the second target position are presented in Figures 5 and 6.

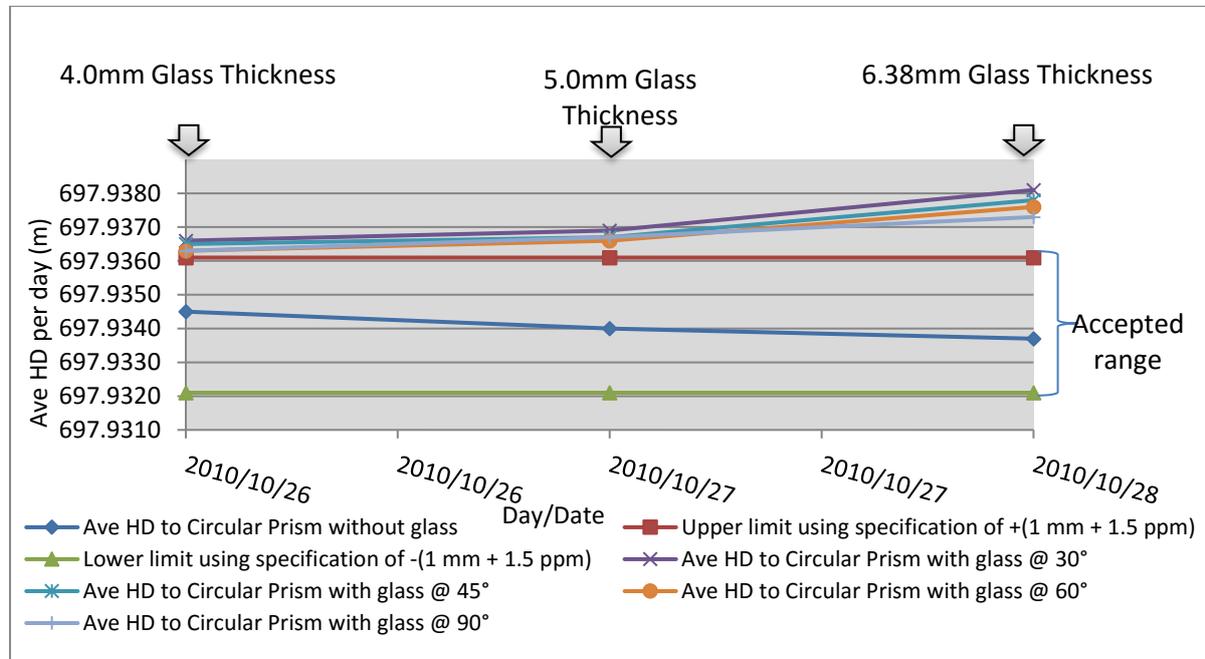


Figure 5: Average HDs to circular prism corrected for prism constant, scale factor and atmospheric corrections, but not corrected for glass thickness impact, as seen in the second target station

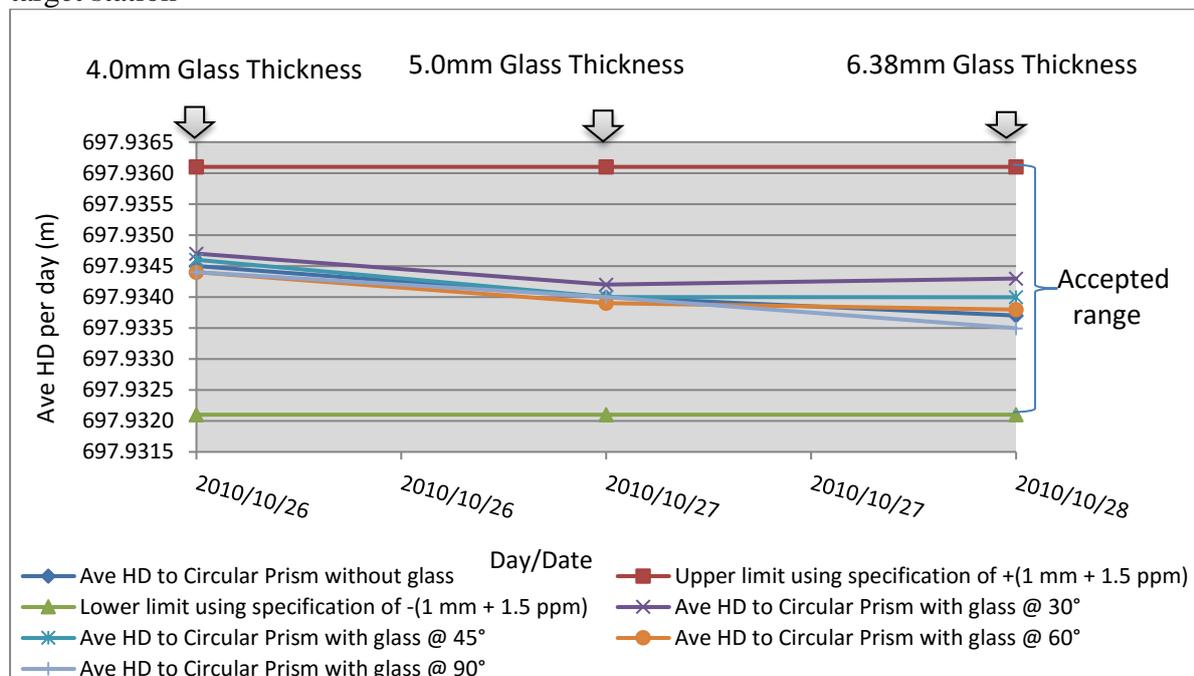


Figure 6: Average HDs to circular prism corrected for prism constant, scale factor, atmospheric and glass thickness, as seen in the second target station

The impact when monitoring the Leica circular prism, as shown in Figure 5, ranged between 1.8mm and 2.1mm when 4.0mm glass was used. It ranged between 2.6mm and 2.9mm when 5.0mm glass was used, while the impact caused by 6.38mm glass ranged between 3.6mm and 4.4mm. The impact also changed after applying the glass-thickness correction formula, as shown in Figure 6. The impact range caused by a 4.0mm glass thickness reduced to -0.1mm and 0.2mm. A 5.0mm glass impact changed to -0.1mm and 0.2mm, while a 6.38mm glass impact changed to -0.2mm and 0.6mm.

3.2 Results and Discussions for Glass Colour (Glass Tint Level).

The result of the data analysis when monitoring the Leica circular prism at the first target position during the glass-colour model test is presented in Figure 7. The graph shows the average daily HD measurements corrected for prism constant, scale factor and atmospheric corrections, but not corrected for glass impact. The result after all corrections, including prism constant, scale factor, atmospheric and glass corrections, is presented in Figure 8.

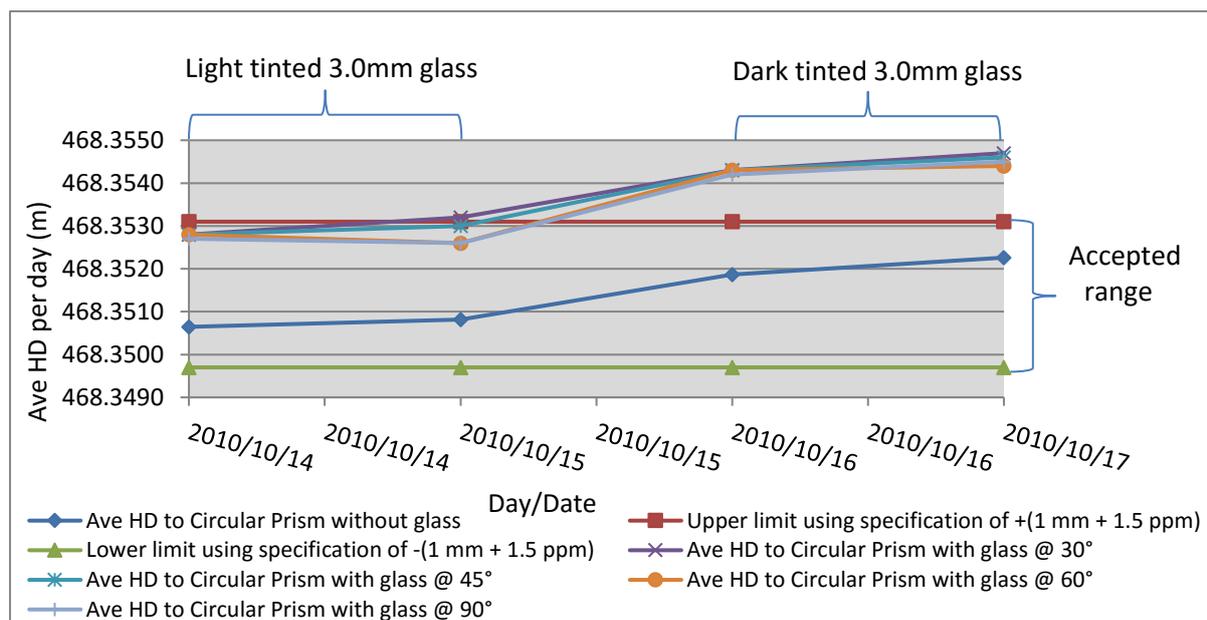


Figure 7: Average HDs to circular prism corrected for prism constant, scale factor and atmospheric corrections, but not corrected for glass thickness impact, as seen in the first target station

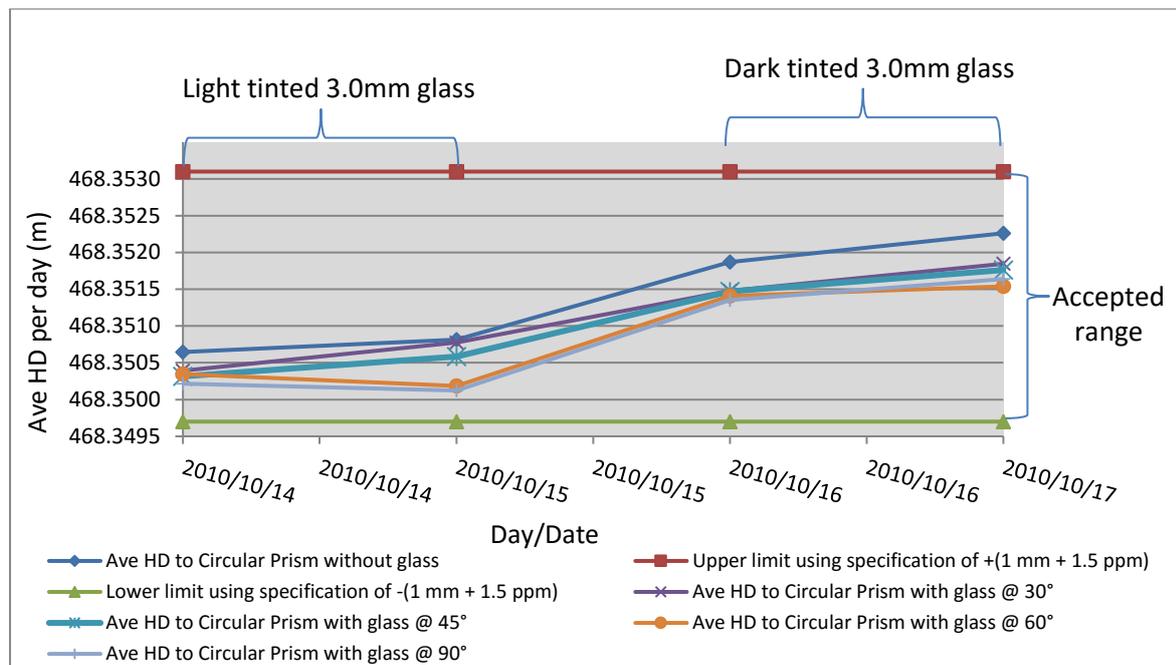


Figure 8: Average HDs to circular prism corrected for prism constant, scale factor, atmospheric and glass thickness, as seen in the first target station

Figure 7 shows the average daily HD measurements to the circular prisms during the glass colour test. In the graph only HD readings without glass fall within the accuracy limits, while all the other HD readings with 5% (light-tinted) and 50% (dark-tinted) tinted glass are outside the accuracy limits. The impact increases with increase in glass tint level. In Figure 7, the impact ranged between 1.8mm and 2.4mm when light-tinted glass was used. It also ranged between 2.1mm and 2.4mm when dark-tinted glass was used. In addition, the situation changed after applying the glass-colour impact correction formula, as shown in Figure 8. The impact caused by 3.0mm light-tinted glass was reduced to -0.7mm and 0.0mm, while the dark-tinted 3.0mm glass impact changed to -0.7mm and -0.4mm after applying the glass-colour impact correction formula to the HD readings.

At the second target station, only HD readings with and without light-tinted glass could be measured. The total station consistently signalled Error 256, meaning that the EDM measurement was not achieved due to detection of multiple targets, targets moving, a break in the beam or air turbulence, when measurements were taken through dark-tinted glass. Therefore, only HDs with and without light-tinted glass were analysed. The results when monitoring the Leica circular prism at the second target station during the glass-colour model test are shown in Figures 9 and 10.

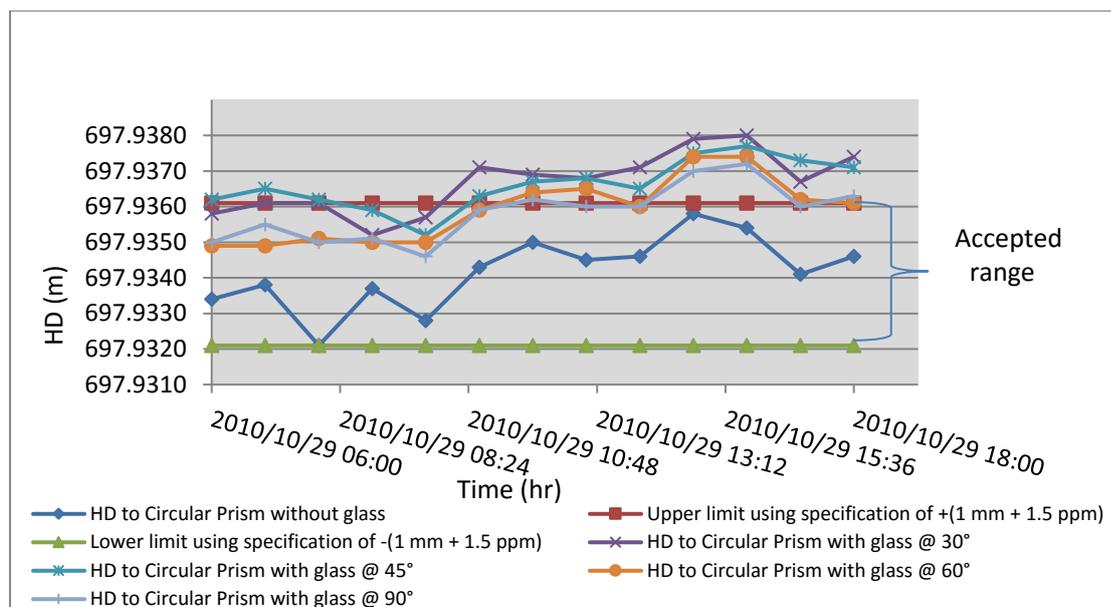


Figure 9: HDs to circular prism after prism constant, scale factor and atmospheric corrections, but before glass colour correction using light tinted 3.0mm glass, as seen in the second target station

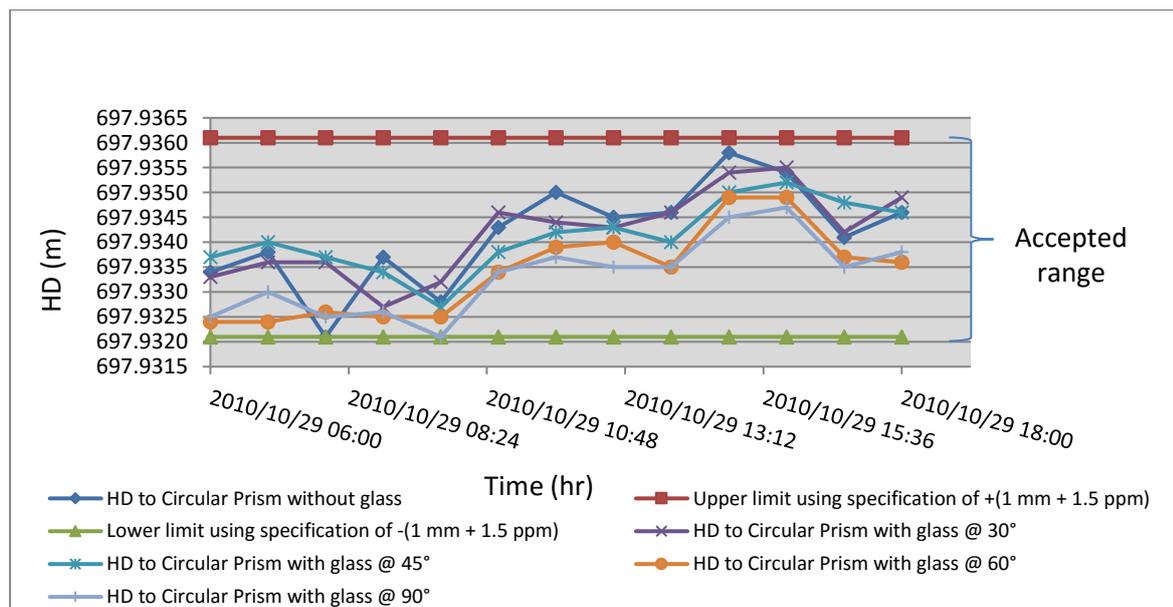


Figure 10: HDs to circular prism after prism constant scale factor, atmospheric and glass colour corrections using light tinted 3.0mm glass, as seen in the second target station

Figure 9 reveals that only HD readings without glass are within the accuracy limits. All the other HDs measured when there was light-tinted glass in place are outside the accuracy limits. The impact caused by the light-tinted glass ranges between 1.2mm and 4.0mm, as evident in Figure 9. The impact also reduced to -1.1mm and 1.6mm after applying the glass-thickness correction formula, as shown in Figure 10.

4. Conclusion and Recommendation

The paper discussed total station survey monitoring and its associated errors. The graphs generated during the data analysis clearly reveal that the TCR 1201 total station used for this research is good for monitoring, since all the HDs measured without glass fell within the accuracy limits specified by the instrument manufacturer. However, distance measurement through glass has an impact on the performance of the total station and must therefore be catered for. The paper also discussed the steps taken to model the systematic error caused by the glass medium. The models generated performed well in reducing this error and ensured that all distances measured through the glass medium fall within the accuracy limits specified by the instrument manufacturer. However, there is a need for further research with regard to the colour aspect of the glass. The glass-colour impact model reveals that the angular positions of the glass have more of an impact on the HD readings when tinted glass panes were used, as opposed to the use of non-tinted glass.

5. Acknowledgement

This paper is part of research project 3.9, financed by Coaltech Research Association, South Africa and the University of the Witwatersrand Johannesburg. The authors are grateful to both sponsors.

6. References

- Afeni, T.B. and Cawood, F.T., 2012. "Do the properties of glass matter when taking total station distance measurements through an observation window? *Journal of the Institute of Mine Surveyor of South Africa, Vol. XXXVI, No. 2, pp 21 – 28.*
- Afeni, T.B. and Cawood, F.T. 2010. "Pre-delivery Calibration on a new Total Station – Geosystems Africa Laboratory Experience". *Journal of the Institute of Mine Surveyor of South Africa. Vol. XXXIV, No. 2, pp. 8 – 19.*
- Bannister, A., Raymond, S. And Baker, R. (1998): *Surveying*. Pearson Education Ltd. Edinburgh Gate, England.502pp.
- Burnside, C.D., 1991. "Electromagnetic Distance Measurement". BSP Professional Books, Great Britain; 3rd Edition, 278pages.

- Duffy, M.A., Hill, C., Whitaker, C., Chrzanowski, A., Lutes, J. And Bastin, G. 2001. "An Automated and Integrated Monitoring Scheme for Diamond Valley Lake in California". Proc. of the 10th FIG Symposium on Deformation Measurements, 19-22 March, Orange, California, USA; 21pp.
- Hill, C.D. and Sippel, K.D. 2002. "Modern, Deformation Monitoring: A Multi Sensor approach". FIG XXII International Congress, Washington GC, USA; 12pp.
- Kuhlmann, H. and Glaser, A. (2002): "Investigation of New Measurement Techniques for Bridge Monitoring." 2nd Symposium on Geodesy for Geotechnical and Structural Engineering, Berlin, Germany.
- Lange, C and Kippelen, D., 2008. "Real-Time Monitoring for Support of Excavation". Geotechnical Engineering, Geo-institute of ASCE (American Society of Civil Engineers), vol. 9, no. 1, pp. 16 – 18.
- Leung, K. 2001. "Automatic Real-time Monitoring System (ARMS) – A Robotic Solution to Slope Monitoring". Proc. of the 10th FIG Symposium on Deformation Measurements, 19-22 March, Orange, California, USA, pp 313-318.
- Lutes, J.A. (2002). "Automated dam displacement monitoring using a robotic total station". Master of Science dissertation, University of New Brunswick, Fredericton, Canada.
- Ostdiek, V.J. and Bord, D.J. (2008): Inquiry into Physics. 6th edition, Thomson Learning Academic Resources Center, 10, Drive, Belmont, CA, USA.
- Palazzo, D., Friedmann, R., Nadal, C., Santos-Filho, M., Veiga, L., and Faggion, P. 2006. "Dynamic Monitoring of Structures using a Robotic Total Station". XXIII FIG Congress, Munich, Germany, Oct. 8-13, 2006; 10pp.
- Radovanovic, R. S. and Teskey, W. F., 2001. "Dynamic Monitoring of Deforming Structures: GPS versus Robotic Tacheometry Systems." The 10th FIG International Symposium on Deformation Measurements, Orange, California, USA, 10pp.
- Rencher, A.C. and Schaalje, G.B. (2007): Linear Models in Statistics. John Wiley & Sons Inc., Hoboken, New Jersey. 672pp.
- Taylor, J.R., 1999. An Introduction to Error Analysis: The Study of Uncertainties in Physical Measurements. University Science Books, 323pp.
- Wyllie, D.C. and Mah, C.W. (2004): Rock Slope Engineering Civil and Mining. Spon Press, Taylor and Francis e-library; 456pp.
- Zahariadis, H. And Tsakiri, M., 2006. "Low Cost Monitoring System in the Open Pit Lignite Mines of Megalopoli, Greece". 3rd IAG/12th FIG Symposium, Baden; 10pp.

Appendix A

The effect of glass on beam of light

The effect of the shelter glass on the beam generated by the total station during monitoring with RTS from transfer beacon shelter is called refractive effects and it is based on Snell's law. This law expresses the relationship between the angles of incidence and refraction, when a light ray passes through a boundary between two different isotropic media, namely air and glass, as in regards to this study. Ostdiek and Bord (2008) simplified the whole process by saying, "a light ray is bent toward the normal when it enters a transparent medium (e.g. glass or water) in which light travels more slowly. It is bent away from the normal when it enters a medium in which light travels faster". Based on Snell's theory, the beam from the RTS passes through the air inside the total station shelter (transfer beacon shelter) and strikes the shelter glass window at an angle of incidence θ' with respect to the surface normal. It refracts and passes through the glass at angle θ_g with respect to the surface normal. The beam is slowed down when passing through the glass, because the refractive index of the glass n_g is greater than the refractive index of the air n_a . When the beam emerges from the glass, it refracts once more so that its angle with respect to the surface normal is again θ and also resumes its original speed. Figure A.1 below demonstrates the whole scenario.

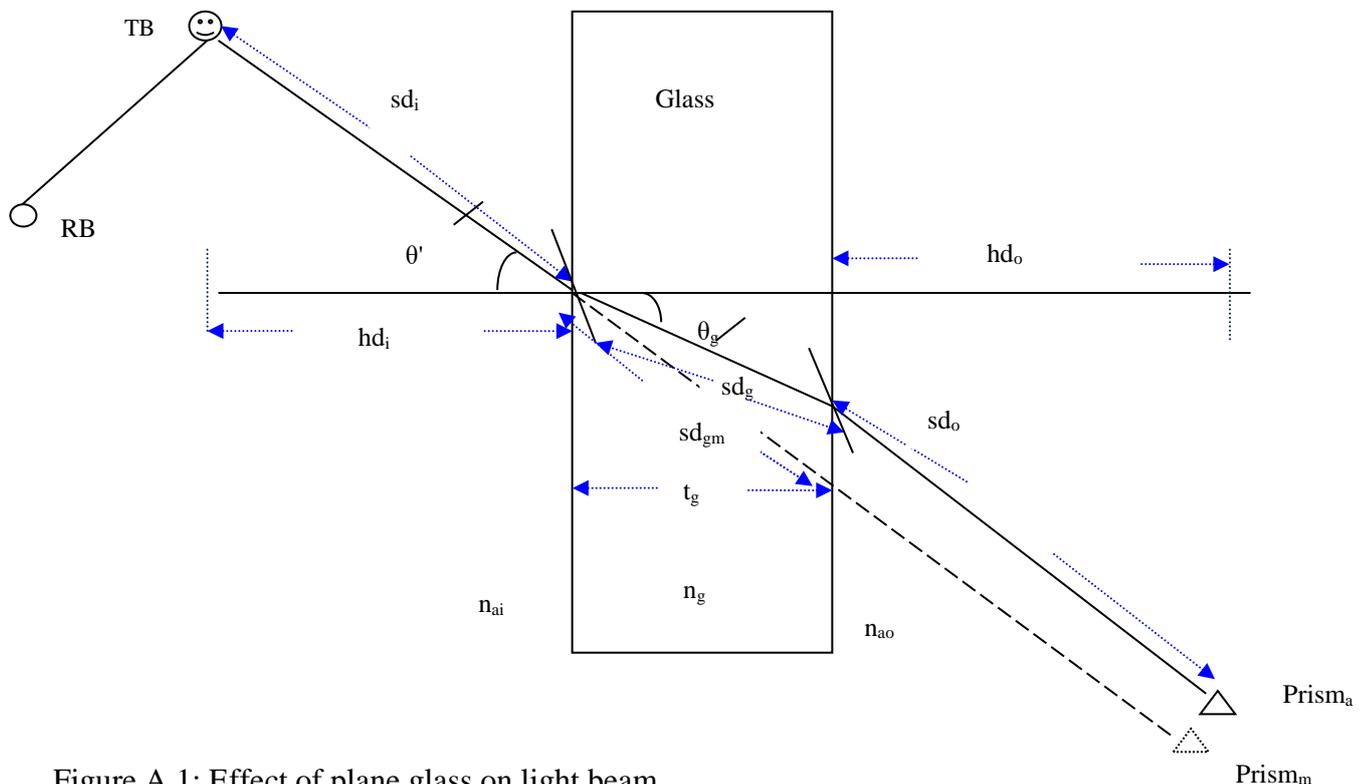


Figure A.1: Effect of plane glass on light beam

where:

- TB is the transfer beacon upon which the RTS is mounted inside the shelter;
- RB is the reference beacon (control point) for orientation;
- θ' is the angle of incidence of the RTS with respect to the surface normal of the glass;
- sd_i is the slope distance between the RTS and the glass;
- hd_i is the horizontal distance between the RTS and the glass;
- n_{ai} is the refractive index of air inside the shelter;
- θ_g is the angle of refraction within the glass;
- sd_g is the slope distance within the glass or distance travelled by the RTS beam through the glass;
- sd_{gm} is the slope distance that would be measured by the RTS through the glass;
- t_g is the thickness of the glass;
- n_g is the refractive index of the glass;
- n_{ao} is the refractive index of air outside the shelter;
- sd_o is the slope distance between the glass and the target, the prism, that is being monitored, while hd_o is the corresponding horizontal distance; and
- $Prism_m$ is the measured prism position, while $Prism_a$ is the actual prism position.

Mathematically, the total slope distance would be:

$$sd_{total} = sd_i + sd_g + sd_o \dots\dots\dots[A1]$$

(where $sd_g = \frac{t_g}{\cos(\theta_g)}$; and $\theta_g = \sin^{-1} \left[\sin(\theta) \times \frac{n_a}{n_g} \right]$)

While horizontal distance would be:

$$hd_{total} = hd_i + t_g + hd_o \dots\dots\dots [A2]$$

Consequently, the actual coordinate of the prism would be:

$$Prism_a (Y_a) = (sd_i + sd_o). \sin(\theta) + sd_g. \sin(\theta_g); \text{ and } Prism_a (X_a) = (sd_i + sd_o). \cos(\theta) + sd_g. \cos(\theta_g) \dots\dots\dots[A3]$$

However, all the above quantities are hardly taken into account, nor are their values known when computing the position of the prism relative to the RTS position. The measured coordinate values that are displayed on the RTS screen are usually computed from:

$$\left. \begin{aligned} Prism_m (Y_m) &= (sd_i + sd_{gm} + sd_o). \sin(\theta); \text{ and } Prism_m (X_m) = (sd_i + sd_{gm} + sd_o). \cos(\theta) \\ \text{I.e. } Prism_m (Y_m) &= sd_{total}. \sin(\theta) \text{ and } Prism_m (X_m) = sd_{total}. \cos(\theta) \end{aligned} \right\} [A4]$$

(where $sd_{gm} = sd_g \times \frac{n_g}{n_{ao}}$)

If the join between the TB and RB is calculated, and the direction from TB to the prism is known by using RB for orientation, for instance α_{tb-p} , the above equation A4, can be re-written as:

$$\left. \begin{aligned} \text{Prism}_m (Y_m) &= [(hd_i + t + hd_o) \cdot \sin (\alpha_{tb-p})] + Y_{TB}; \text{ and } \text{Prism}_m (X_m) = [(hd_i + t_g + \\ &hd_o) \cdot \cos (\alpha_{tb-p})] + X_{TB} \\ \text{i.e. } \text{Prism}_m (Y_m) &= [hd_{total} \cdot \sin (\alpha_{ts-p})] + Y_{TB}; \text{ and } \text{Prism}_m (X_m) = [hd_{total} \cdot \cos (\alpha_{tb-p})] + \\ &X_{TB}. \end{aligned} \right\} [A5]$$

where:

α_{tb-p} is the direction of prism from the instrument station TB; and

Y_{TB} and X_{TB} are the coordinates of instrument station TB or the transfer beacon.

The displayed coordinate on the screen of the RTS are based on equations A4 and A5.

According to Lutes (2002), this is based on the assumptions that:

- a. the glass is perfectly flat on both sides;
 - b. the inside and outside surfaces of the glass are parallel;
 - c. the glass molecules are pure, i.e. without bubbles in the inner structure of the glass;
 - d. the glass refractive index is uniform;
 - e. the refractive index of air inside the shelter is identical to that outside of the shelter;
- and
- f. the refractive index of the air is uniform.

Practically, the above assumptions are not attainable. Therefore, there is a need to examine the effect of the shelter glass on the quality of distances measured with a total station setup in a transfer beacon shelter.

Computation of Refractive Effects on Distance Measurements

During distance measurement to the short monitoring target, the following were recorded:

- $t_g = 3.0 \text{ mm}$ Thickness of the glass
- $\theta' = 60^\circ$ Angle of incidence of total station beam with shelter glass
- $n_{ao} = 1.00028$ Refractive index of air (see Table 2.6 in chapter two)
- $n_g = 1.52$ Refractive index of shelter glass (see sub-section 4.2.5 in chapter four)

The angle of refraction of the total station beam

Using equation A1 in chapter two:

$$sd_{total} = sd_i + sd_g + sdo \dots\dots\dots[A1]$$

(where $sd_g = \frac{t_g}{\cos(\theta_g)}$; and $\theta_g = \sin^{-1} \left[\sin(\theta) \times \frac{n_a}{n_g} \right]$)

θ_g is the angle of refraction within the glass;

sd_g is the actual distance within the glass that the beam is supposed to travel

$$\theta_g = \sin^{-1} \left[\sin 60 \times \frac{1.00028}{1.52} \right] = 34.7^\circ$$

$$sd_g = \frac{3}{\cos 34.7} = 3.65 \text{ mm}$$

The measured distance within the glass by the total station is sd_{gm} (see equation A4 above):

$$\text{Prism}_m (Y_m) = (sd_i + sd_{gm} + sdo) \cdot \sin(\theta); \text{Prism}_m (X_m) = (sd_i + sd_{gm} + sdo) \cdot \cos(\theta);$$

(where: $sd_{gm} = sd_g \times \frac{n_g}{n_{ao}} = 3.65 \times \frac{1.52}{1.00028} = 5.546 \text{ mm}$)

The difference between the actual distance sd_g that the RTS is supposed to measure and the measured distance sd_{gm} is the refractive effect caused by the glass material.

Refractive effect of 3.0mm glass = $5.546 - 3.65 = 1.89\text{mm}$

Using the same procedures, the sd_g for 4.0mm, 5.0mm and 6.38mm would be: 4.868mm, 6.085mm and 7.764mm, while the corresponding sd_{gm} would be: 7.3967mm, 9.246mm and 11.798mm.

Therefore, their refractive effects would be: 2.51mm, 3.2mm and 4.03mm.

These can be summarised in the Table below:

Difference between the physical model and the regression model results

Glass thickness	Physical model (mm)	Regression model (mm)	Difference (mm)
3	1.89	1.70	0.19
4	2.51	2.40	0.11
5	3.20	3.10	0.10
6.38	4.03	4.07	0.04

The variation is very small (i.e. less than 0.2mm). This is an indication that the regression model developed is effective despite being a much simpler approach. However, the little variation may be as a result of non-attainability of the assumptions highlighted in Lutes (2002) as stated above.