

STOCHASTIC MODEL FOR THE PREDICTION OF SHORT TIME NUMBER OF FIRE ACCIDENT OCCURRENCE IN NIGER STATE USING VITERBI ALGORITHM

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ABSTRACT

In this paper, we look into ways by which fire outbreak (accident) can be suppressed. A stochastic model that predicts the number of fire accident occurrence in Niger State using Viterbi Algorithm is presented. A three-State stochastic model was formulated using the principle of Markov and each state of the model has four possible observations. The parameters of the model were estimated using the fire accident data collected from the archive of Niger State Fire Service, after which the model was trained using Baum-welch Algorithm to attend maximum likelihood. The Validity test for the model recorded 75% accuracy for short time prediction and shows 50% accuracy for long time prediction. This indicates that the model is more reliable and dependable for short time prediction. Information for this study could serve as a guide to the government in policy formulation that might assist in curbing the number of fire accident occurrences in Niger State.

Keyword: Hidden Markov Model, Transition Probability, Observation Probability, Fire accident Occurrence, Viterbi Algorithm

INTRODUCTION

Fire is the rapid oxidation of a material in the exothermic chemical process of combustion, releasing heat, light, and various reaction products (Charles, 2000). Fires start when a flammable and/or a combustible material, in combination with a sufficient quantity of an oxidizer such as oxygen gas or another oxygen-rich compound is exposed to a source of heat or ambient temperature above the flash point for the fuel and is able to sustain a rate of rapid oxidation that produces a chain reaction (Yusuf, 2012). Fires are both

natural and social phenomena that cause extensive harm to societies in terms of human lives, economic losses, and operational costs (Corcoran *et al.*, 2011; Corcoran and Higgs, 2013; Jennings, 2013; spatenkova and Virrantaus, 2013). Fires also affect communities, their livelihoods and productivity, and can create serious damage and havoc to urban infrastructure, reserved or unreserved (Jennings, 2013 and Corcoran, 2007). All types of fire that is residential fires pose the greatest risk to human lives and the surrounding environment because of their higher likelihood to lead to fatal consequences

(Ceyhan *et al.*, 2013). The complexity of people's behaviour at an individual and collective level in cities has made fire risk extremely complicated to model and theorize (Corcoran *et al.*, 2011; Jennings, 2013; Spatenkova and Virrantaus, 2013). While the number of studies have been increasing in recent years, the current knowledge about the spatial aspects of fire risk is still limited to a few studies mostly from developed countries, such as the United Kingdom (UK), Australia, Canada, Sweden and Finland (Corcoran *et al.* 2007; Chhetriet *al.*, 2010; Asgaryet *al.*, 2010; Corcoran *et al.*, 2011; Spatenkova and Virrantaus 2013; Wuschkeet *al.* 2013; Guldakeret *al.* 2018; Ardianto and Chhetri 2019).

Dry weather has been identified as the major cause of the recent spate of incidents while storing of petrol in living houses and markets, careless disposal of cigarette stubs, adulterated fuel, power surge, electric sparks and illegal connection of electricity are all sources of fire outbreaks. Many people have faulted the responsiveness of fire services and emergency first responders in the country, who have been reputed to always arrive late and without sufficient equipment to the scene of fire incidents. There have also been renewed calls for the federal and state governments to adequately fund the fire department and emergency agencies, and the culture of insuring properties is not imbibed by Lagos residents to mitigate the damage and misery of the misfortune (Yusuf, 2012). Many countries have introduced, or are planning to introduce in the near future, performance-based codes by the use of engineering analysis of fire development and occupant evacuation. The performance-based codes were considered

and the level of safety provided to the occupants in a building by a particular fire safety design were assessed Central to this performance, based on the approach that was used for a suitable design fires that can characterize typical fire growth in a fire compartment. Pantousaet *al.* (2017), developed a Fire-Structure Interface (FSI) simplified dual-layer model. The model calculates the temporal evolution of the gas-temperature in the fire compartment in every virtual zone which is divided in two layers (hot and cold layer). Sakurahara *et al.* (2018), developed an integrated probabilistic risk assessment methodological framework for Fire PRA. The Fire Simulation Module (FSM), includes state-of-the-art models of fire initiation, fire progression, post-fire failure damage propagation, fire brigade response, and scenario-based damage is used in simulation using a computational fluid dynamics (CFD) code, fire dynamics simulator.

The outbreak of fire in Niger State and some other parts of the country is one of the challenging situation faced by inhabitants of this geographical location as in most cases lives and properties worth millions of naira are lost. Fire accident could be very difficult to combat/fight as it can emanate from diverse sources. Prediction of fire accident has been a task to researchers for several decades, because its occurrence is stochastic in nature.

Hence the need to use a stochastic model with pattern recognition capability based on the empirical data to conceivably capture the behavior of the system become paramount. It is on this note, that Hidden Markov Model is selected for this purpose.

Hidden Markov models are extensions of Markov models where each observation is the result of a stochastic process in one of several unobserved states. Hidden Markov model is very influential in stochastic because of its track record of unraveling hidden parts of a complex system and make prediction with high level of accuracy. Hidden Markov Models have been successfully applied in the following

areas; automatic speech recognition and speech synthesis (Rabiner, 1989), identification and inverse filtering (Robert Mattila, 2020), molecular biology for DNA and protein sequencing (Durbin *et al.*, 1998), pattern recognition (Fink, 1989) and in rainfall pattern prediction (Lawal, 2018), Rice yield forecast (Yahaya and Lawal, 2020).

METHODOLOGY

a. Hidden Markov Model

A Hidden Markov Model (HMM) is a double stochastic process in which one of the stochastic processes is an underlying Markov chain which is called the hidden part of the model, the other stochastic process is an observable one. Also a HMM can be considered as a stochastic process whose evolution is governed by an underlying discrete (Markov chain) with a finite number of states which are hidden, i.e. not directly observable (Enza and Daniele, 2007)

b. Characteristics of Hidden Markov Model

Hidden Markov Model is characterized by the following

- N = number of states in the model
- M = number of distinct observation symbols per state
- Q = state sequence

$$Q = q_1, q_2, q_3, \dots, q_T$$

O = observation sequence

$$O = o_1, o_2, o_3, \dots, o_T$$

Transition probability matrix $A = \{a_{ij}\}$

Observation probability matrix $B = \{b_j(o_t)\}$

where $b_j(o_t) = p(o_t | q_t = s_j)$

If the observation is continuous a probability density function is used as follows:

$$\int_{-\infty}^{+\infty} b_j(x) dx = 1$$

$\pi = \{\pi_j\}$ Initial state probabilities

$\lambda = (A, B, \pi)$ The overall HMM

c. Model Formulation

Fire accidents are influenced by many complex factors such as environment, climate, Fire investment, public fire safety consciousness and so on, the statistical data of fire accidents always take on the characteristic of both randomness and fluctuations (Sun and Mao 2011). Since the fire accident occurrence depends on these factors and these factors are not static both varies along the quarters of the year this means that, the number of occurrence of fire accident also varies along the quarters of the year. This situation is stochastic in nature and of the double type. This means that the number of occurrence of fire accident in each quarter of the years varies and the factor influencing the occurrence of the fire accident also varies along the quarters of the year. In general, fire accident occurrence among quarters of the year is a double stochastic process. It is based on this that HMM is being adapted to model number of fire accident occurrence in Niger State.

Now, Let the number of fire accident occurrence within the quarters of the year be taken as the state of the model and the factors influencing fire accident occurrence within the quarters be taken as emission of the Hidden Markov Model, hence we have the following model assumptions

- (i) The transition between the states is governed by first order Markov dependency as represented in equation (1)

$$P\{X_{n+1} = j | X_0 = i_0, \dots, X_{n-2} = i_{n-2}, X_{n-1} = i_{n-1}, X_n = i\} = P_{ij} \quad (1)$$

- (ii) The probability of generating current observation symbol depends on current state, as represented by equation (2)

$$P(O | Q, \lambda) = \prod_{t=1}^T P(o_t | q_t, \lambda) \quad (2)$$

- (iii) The number of fire accident occurrence in a year is considered be low, if it is less than 83
- (iv) The number of fire accident occurrence in a year is considered to be moderate, if it is within the range (83 - 159)
- (v) The number of fire accident occurrence in a year is considered to be high, if it is above 159

Hence, we have the following states and observations for the Hidden Markov Model of fire accident occurrence prediction in Niger state

State 1: Low Fire accident occurrence

State 2: Moderate Fire accident occurrence

State 3: High Fire accident occurrence

Observations:

$Q_1 = O_1 =$ Quarterly (January to March)

$Q_2 = O_2 =$ Quarterly (April to June)

$Q_3 = O_3 =$ Quarterly (July to September)

Q₄= O₄ = Quarterly (October to December)

The classification of states and the observations, and the assumption made in this work are based on the study area and the data obtained

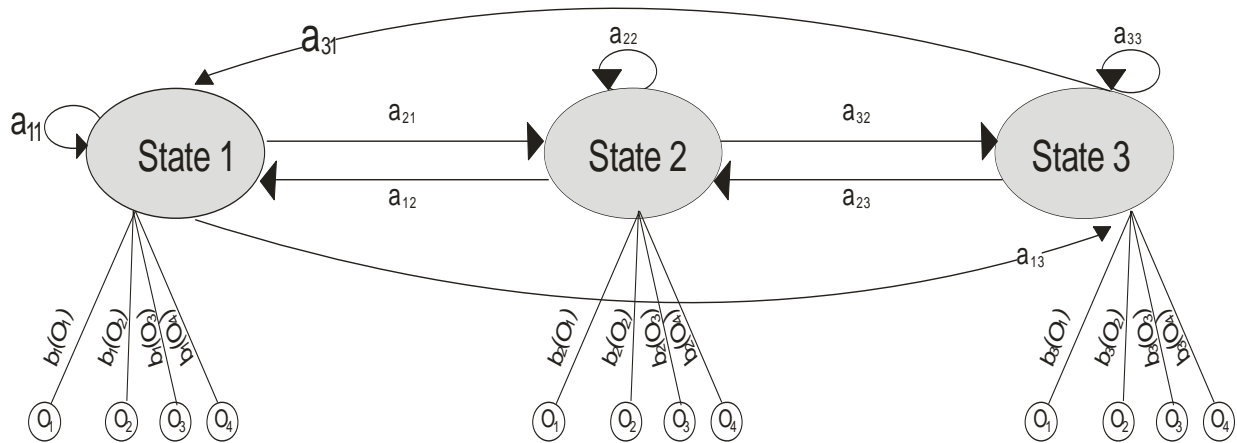


Figure 1: Transition Diagram of the Fire Accident Occurrence Model

Transition Probability Matrix

The transition between the states are represented by equation (3)

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \tag{3}$$

Observation probability matrix

The matrix below represents observation emitted from the model

$$B = \begin{bmatrix} b_1(O_1) & b_1(O_2) & b_1(O_3) & b_1(O_4) \\ b_2(O_1) & b_2(O_2) & b_2(O_3) & b_2(O_4) \\ b_3(O_1) & b_3(O_2) & b_3(O_3) & b_3(O_4) \end{bmatrix} \tag{4}$$

Initial probability distribution

The initial probability distribution for the model is given below

$$\pi = [\pi_1, \pi_2, \pi_3] \tag{5}$$

The Hidden Markov Model for Fire Accident Occurrence

The general Hidden Markov Model for the number of fire accident occurrence prediction is given by the compact notation in equation (6)

$$\lambda = (A, B, \pi) \tag{6}$$

RESULTS**Application of the Hidden Markov Model for Prediction of Fire accident Occurrence**

The data used in this research work were collected from the Niger State Fire service for the period of 8 years (20013 – 2020). Niger state with a population of 5,556,247 million people (National population commission, 2020) is located in the North central zone along the Middle Belt region of Nigeria. It is classified as one of the largest states in the country (in terms of landmarks), spanning over 86,000 km² in land area. The summary is presented in Table 1 below

Table 1: Summary of State and Observation of Fire Occurrence for a Period of Eight Years

Years	States	Observations
2013	1 (L)	(Q ₁)
	1(L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(Q ₄)
2014	1(L)	(Q ₁)
	1(L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(Q ₄)
2015	1(L)	(Q ₁)
	1(L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(Q ₄)
20016	1(L)	(Q ₁)
	1(L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(O ₄)
2017	2(M)	(Q ₁)
	1 (L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(Q ₄)
2018	2(M)	(Q ₁)
	1(L)	(Q ₂)
	1(L)	(Q ₃)
	1(L)	(Q ₄)
2019	2(M)	(O ₁)
	2(M)	(Q ₂)
	1(L)	(Q ₃)
	2(M)	(Q ₄)

2020	3(H)	(Q ₁)
	2(M)	(Q ₂)
	1(L)	(Q ₃)
	2(M)	(Q ₄)

Validity Test for the Model

To test for the validity of the model, the parameters of the HMM were estimated using the fireaccident occurrence data from 2013 to 2017, then make forecast for 2018, 2019 and 2020.

The Transition Count Matrix (C), Pseudo count Transition Matrix (S) and Transition Probability Matrix (A) are given in Equations (7), (8) and (9) respectively.

$$C = \begin{bmatrix} 17 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (7)$$

$$S = \begin{bmatrix} 18 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad (8)$$

$$A = \begin{bmatrix} 0.8571 & 0.0952 & 0.0476 \\ 0.5000 & 0.2500 & 0.2500 \\ 0.3333 & 0.3333 & 0.3333 \end{bmatrix} \quad (9)$$

While Observation count matrix (E), Pseudo count Observation matrix (D) and Observation probability matrix (B) are given in equations (10), (11) and (12), respectively.

$$E = \begin{bmatrix} 4 & 5 & 5 & 5 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad (10)$$

$$D = \begin{bmatrix} 5 & 6 & 6 & 6 \\ 2 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \quad (11)$$

$$B = \begin{bmatrix} 0.625 & 0.750 & 0.750 & 0.750 \\ 0.250 & 0.125 & 0.125 & 0.125 \\ 0.125 & 0.125 & 0.125 & 0.125 \end{bmatrix} \quad (12)$$

The initial state probability is given below

$$\pi = [0.95, 0.05, 0] \quad (13)$$

The general HMM1 is represented by equation (14)

$$\lambda_1 = (A, B, \pi) \quad (14)$$

After 1000 iteration of the Baum Welch Algorithm, Theequation stabilised to equation(15) we trained equation (14) using a built-in Baum algorithm function in the Matlab 2015.

$$\lambda_1^* = \left(\hat{A}, \hat{B}, \hat{\pi} \right) \quad (15)$$

where

$$\hat{A} = \begin{bmatrix} 0.5556 & 0.4444 & 0.0000 \\ 0.0000 & 0.0000 & 1.0000 \\ 1.0000 & 0.0000 & 0.0000 \end{bmatrix} \quad (16)$$

$$\hat{B} = \begin{bmatrix} 0.000 & 0.000 & 0.500 & 0.500 \\ 1.000 & 0.000 & 0.000 & 0.000 \\ 0.000 & 1.000 & 0.000 & 0.000 \end{bmatrix} \quad (17)$$

$$\text{And } \pi = [0.95, 0.05, 0] \quad (18)$$

Making Prediction with the Model

From the summary of the fire accident data presented in table 1, the process is in State 1at the last Quarter of 2017 (that is with Observation Q₄). Now, to obtain the likely state sequence of the process in 2018 given the observation sequence of the year 2018 that is Q₁, Q₂, Q₃ and Q₄, we use Viterbi algorithm as shown in figure 1

To avoid underflow of the Viterbi algorithm, we normalised each of the obtained node in the computation process using the following equations:

$$c_t = \frac{1}{\sum_{i=1}^N \alpha_t(i)} \quad (19)$$

$$\hat{\alpha}_t(i) = c_t \times \alpha_t(i) = \frac{\alpha_t(i)}{\sum_{i=1}^N \alpha_t(i)} \quad (20)$$

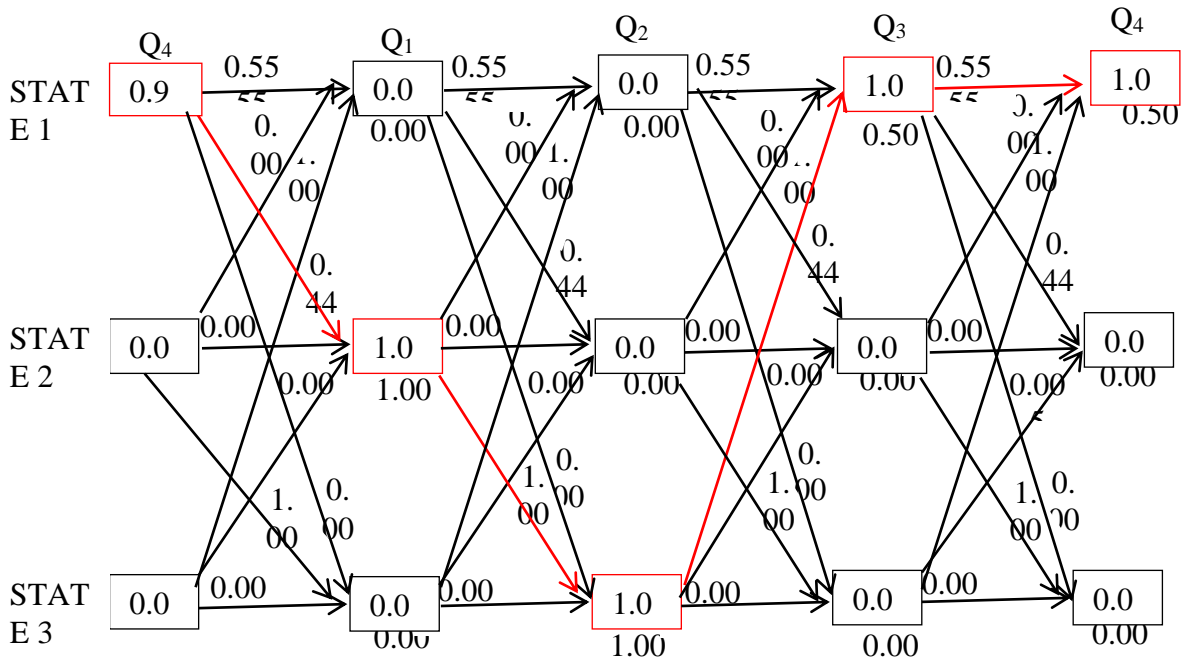


Figure 2: Viterbi algorithm for Observation Sequence Q₄,Q₁,Q₂,Q₃Q₄of 2018

State 1 to state 2, has the highest probability value under Q₁ that is, $(0.95 \times 0.44)1.00=0.4222$, normalising this value using equation (19) and (20) we obtain the value 1, then we move to the next path of computation.

State 2 to state 3, has the highest probability value under Q₂ that is $(0.05 \times 1.00)1.00=0.0500$, normalising this value using equation (19) and (20) we obtain the value 1, then we move to the next path of the computation.

State 3 to state 1, has the highest probability value under Q₃ that is $(0.95 \times 0.55)0.50=0.2639$, normalising this value using equation (19) and (20) we obtain the value 1, then we move to the next path of the computation.

State 1 to state 1, has the highest probability value under Q₄ that is, $(0.95 \times 0.55)0.50=0.2636$, normalising this value using equation (19) and (20)we obtain the value 1, The results of the computation of figure 2 are represented in Table 2 below.

Table 2: The Result for 2018 Number of FireAccident Occurrence Based on Viterbi Algorithm Prediction

Year/Months	2017		2018		
States:	1	2	3	1	1
Observation:	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄

Similarly, from the calculation of Table 2, the process is in State 1 at the last Quarter of 2018 (that is with Observation Q₄). Now, to obtain the likely state sequence of the process in 2019 given the observation sequence of the year 2019 that is Q₁, Q₂, Q₃ and Q₄, we use Viterbi algorithm as shown in figure 3. To avoid underflow of the Viterbi algorithm we normalised

each of the obtained node in the computation process using the following equations (19) and (20)

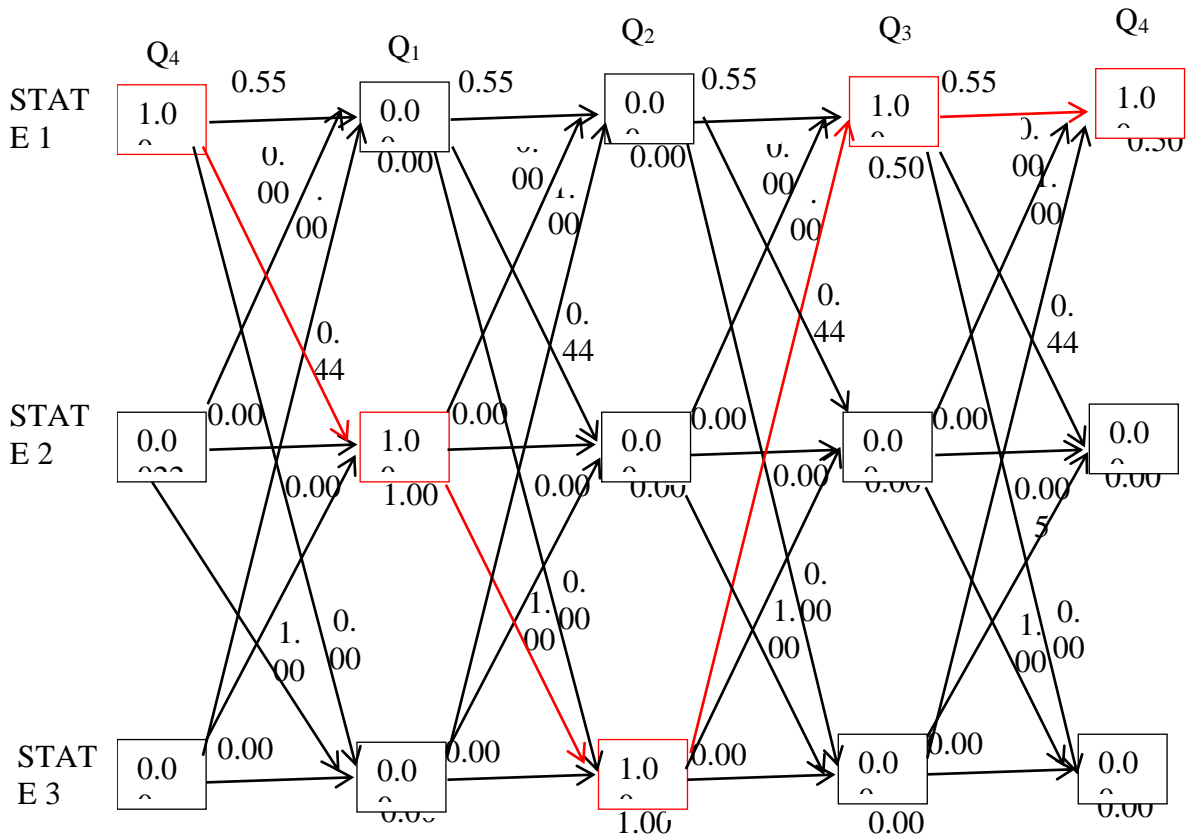


Figure 3: Viterbi algorithm for Observation Sequence Q4,Q1,Q2,Q3Q4of 2019

State 1 to State 2, has the highest probability value under Q₁ that is $(0.444 \times 1.00)1.00=0.444$, normalising this value using equation (19) and (20)we obtain the value 1,

State 2 to State 3, has the highest probability value under Q₂ that is, $(1.000 \times 1.000)1.00=1.000$, normalising this value using equation (19) and (20) we obtain the value 1.

State 3 to state 1, has the highest probability value under Q₃ that is, $(1.000 \times 1.000)0.50= 0.50$, normalising this value using equation (19) and (20) we obtain the value 1.

State 1 to state 1, has the highest probability value under Q₄ that is, $(1.000 \times 0.55)0.50 = 0.2775$, normalising this value using equation (19) and (20) we obtain the value 1.

The results of the computation of figure 3 are represented in Table 3.

Table 3: The Result for 2019 Number of FireAccident Occurrence Based On Viterbi Algorithm Prediction

Years	2019			
States	2	3	1	1
Observation	Q ₁	Q ₂	Q ₃	Q ₄

Similarly, the process is in State 1 at second Quarter of 2019 (that is with Observation Q₄). Now, to obtain the next likely state sequence of the process in 2020 given the observation sequence of the year 2020 that is Q₁, Q₂, Q₃ and Q₄, we use Viterbi algorithm as shown in figure 4.

To avoid underflow of the Viterbi algorithm we normalised each of the obtained node in the computation process using the following equations (19) and (20).

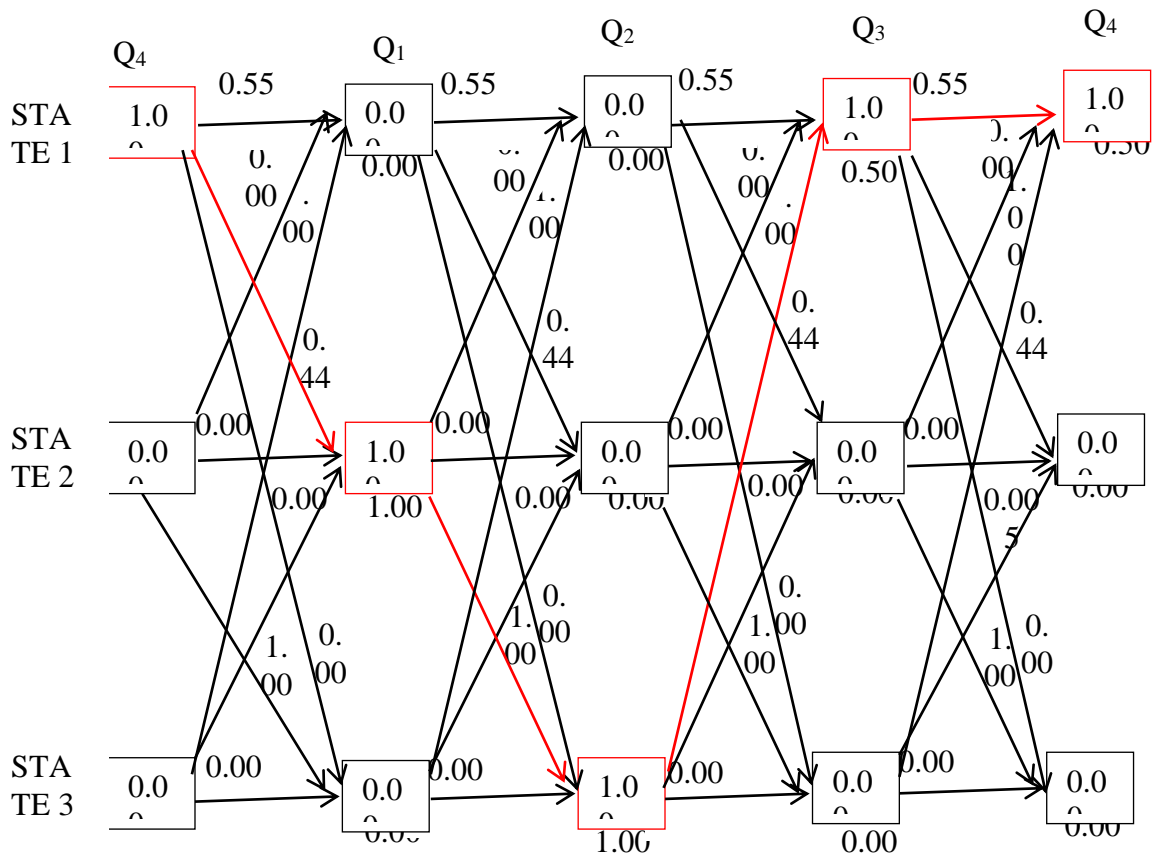


Figure 4: Viterbi algorithm for Observation Sequence Q₄, Q₁, Q₂, Q₃, Q₄ of 2020

state 1 to state 2, has the highest probability value under Q₁ that is $(0.444 \times 1.00)1.00=0.444$, normalising this value using equation (19) and (20) we obtain the value 1,

State 2 to state 3, has the highest probability value under Q₂ that is, $(1.000 \times 1.000)1.00=1.000$, normalising this value using equation (19) and (20) we obtain the value 1,

State 3 to state 1, has the highest probability value under Q₃ that is, $(1.000 \times 1.000)0.50= 0.50$, normalising this value using equation (19) and (20) we obtain the value 1,

State 1 to state 1, has the highest probability value under Q₄ that is, $(1.000 \times 0.55)0.50 = 0.2775$, normalising this value using equation (19) and (20) we obtain the value 1,

The results of the computation of figure 4 are represented in Table 4 below.

Table 4: The Result for 2020 Number of FireAccident Occurrence Based On Viterbi Algorithm Prediction

Year	2020			
States	2	3	1	1
Observation	Q ₁	Q ₂	Q ₃	Q ₄

In general, the summary of the fire accident occurrence which shown below in table 5

Table 5: Summary of the Fire Accident Occurrence

Year	2018				2019				2020			
States	2	3	1	1	2	3	1	1	2	3	1	1
Observation	Q ₁	Q ₂	Q ₃	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄

Table 6: Comparison of the Predicted States and Observations, and the Actual States and Observations from Table 1.

Year	2018				2019				2020			
Actual States	2	1	1	1	2	2	1	2	3	2	1	2
Predicted States	2	3	1	1	2	3	1	1	2	3	1	1
Observation	Q ₁	Q ₂	Q ₃	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄

From the table 6, it can be observed that the prediction for 2018 Quarters has 75% accuracy, then 2018 to 2019 Quarters has 62.5% accuracy and lastly for 2018 to 2020 has 50% accuracy. The result of the model clearly shows that, the model perform better for only short time prediction and perform fairly for long time prediction.

Hidden Markov Model for future prediction

Hidden Markov model for future prediction is developed to predict number of Fire Accident Occurrence for future years, the parameters of the model were determined using Fire Accident Occurrence data from 2013 to 2020 (the whole data set) after which, we predict for 2021 and 2022.

Transition Count Matrix

$$C = \begin{bmatrix} 19 & 5 & 0 \\ 4 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad (21)$$

Pseudo count Transition Matrix

$$S = \begin{bmatrix} 20 & 6 & 1 \\ 5 & 2 & 2 \\ 1 & 2 & 1 \end{bmatrix} \quad (22)$$

Transition Probability Matrix

$$A = \begin{bmatrix} 0.7407 & 0.2222 & 0.0370 \\ 0.5555 & 0.2222 & 0.2222 \\ 0.2500 & 0.5000 & 0.2500 \end{bmatrix} \quad (23)$$

Observation Count Matrix

$$C = \begin{bmatrix} 4 & 6 & 8 & 6 \\ 3 & 2 & 0 & 2 \\ 1 & 0 & 0 & 0 \end{bmatrix} \quad (24)$$

Pseudo count Observation Matrix

$$S = \begin{bmatrix} 5 & 7 & 9 & 7 \\ 4 & 3 & 1 & 3 \\ 2 & 1 & 1 & 1 \end{bmatrix} \quad (25)$$

Observation Probability Matrix

$$B = \begin{bmatrix} 0.4545 & 0.6363 & 0.8181 & 0.6363 \\ 0.3636 & 0.2727 & 0.0909 & 0.2727 \\ 0.1818 & 0.0909 & 0.0909 & 0.0909 \end{bmatrix} \quad (26)$$

Initial State Probability

$$\pi = [0.75 \quad 0.2187 \quad 0.0312] \quad (27)$$

$$\lambda_2 = (A, B, \pi) \quad (28)$$

After 900 iteration of Baum Welch Algorithm, equation (28) stabilized to (29)

$$\lambda^* = \left(\hat{A}, \hat{B}, \hat{\pi} \right) \quad (29)$$

Where

$$\hat{A} = \begin{bmatrix} 0.5333 & 0.4667 & 0.0000 \\ 0.0000 & 0.0000 & 1.0000 \\ 1.0000 & 0.0000 & 0.0000 \end{bmatrix} \quad (30)$$

$$\hat{B} = \begin{bmatrix} 0.0000 & 0.0000 & 0.6000 & 0.4000 \\ 1.0000 & 0.0000 & 0.0000 & 0.0000 \\ 0.0000 & 1.0000 & 0.0000 & 0.0000 \end{bmatrix} \tag{31}$$

$$\hat{\pi} = [0.75 \quad 0.2187 \quad 0.0312] \tag{32}$$

Prediction for 2021 and 2022

Following similar method of prediction procedures and using equation (30) to (32) the results for 2021 and 2022 predictions are presented in the table 7 below

Table 7: The Result for 2021 and 2022 Number Of Fire Accident Occurrence Based on Viterbi Algorithm Prediction

Year	2020		2021				2022			
States:	1	2	3	1	1	2	3	1	1	
Observation:	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄	Q ₁	Q ₂	Q ₃	Q ₄	

DISCUSSION OF RESULTS

The parameter of the validity test model was determined using fire Accident Occurrence data from 2013 to 2017. After 1000 iterations of the Baum Welch Algorithm, λ_1 stabilised to a new model λ_1^* , Viterbi Algorithm was then used to make a prediction for Fire Accident Occurrence for 2018, 2019, and 2020. From the table 1, the HMM1 was in state 1 at 2017 last Quarter (Q₄), It make transition to state 2 in 2018 emitting observation (Q₁), then it make move to state 3 emitting observation (Q₂), at that point, it also make move to state 1 emitting observation (Q₃), it then make move to state 1 emitting observation (Q₄). The Validity test for the Quarters of 2018 shows 75% Accuracy.

Similarly in 2019 the process is in state 2 first Quarter (Q₁), then make move to state 3 emitting observation (Q₂), at that point, it also make move to state 1 emitting observation (Q₃), it also make move to state 1 emitting observation (Q₄). The validity test

for 2018 and 2019 Quarters showed 62.5% Accuracy.

Similar interpretation is given in 2020, the process is in state 2 at first Quarter of 2020 (Q₁), then it make move to state 3 emitting observation (Q₂), at that point, it also make move to state 1 emitting observation (Q₃), it also make move to state 1 emitting observation at (Q₄). The validity test for 2018, 2019 and 2020 shows 50% Accuracy.

Generally, the result for the validity test showed that the model perform better for short time prediction and performed fairly for long time prediction.

For the Future prediction the parameter of the HMM were estimated using Fire Accident Occurrence data from 2013 to 2020. After 900 iteration of the Baum Welch algorithm λ_2 , stabilised to another model λ_2^* , the Viterbi Algorithm was then used to make a prediction for future Quarters. From the table 1, the HMM was in

state 2last Quarter of 2020, then it make move to state 2 emitting observation(Q_1)in 2021, at that point, it also make move to state 3emitting observation(Q_2),it also make move to state 1emitting observation(Q_3)it also make move to state 1emitting observation(Q_4) at 2021.

Similar interpretation is given to the movement instate 2 emitting observation(Q_1), at 2022at that point, it also make move to state 3emitting observation(Q_2),it also make move to state 1emitting observation(Q_3), it also make move to state 1emitting observation(Q_4)at year 2022.

CONCLUSION

The study has developHidden Markov Model that predicts the number of fire accident occurrence in Niger State using Viterbi Algorithm. The Validity test for the model showed 75% accuracy for short time prediction and shows 50% accuracy for long time prediction. The result indicates that the model is more reliable and dependable for only short time prediction. Information for this study could serve as a guide to the government in policy formulation that might assist in curbing the number of fire accident occurrences in Niger State.

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