

Multi-objective convex programming problem arising in multivariate sampling

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Abstract

In this paper, we formulate the multivariate allocation problem as a multi-objective convex programming problem. The objective functions are convex and there is a single linear constraint with some upper and lower bounds. We also consider a two dimensional multivariate problem when the cost is minimized. A numerical example is given to illustrate the solution procedure.

Keywords: Multivariate stratified sampling, convex programming, multi-objective problem

1. Introduction

In multivariate surveys, there are more than one population characteristics to be estimated and usually these characteristics are of conflicting nature. The derivation of the optimal sample numbers among various strata or various stages thus requires some special treatment. However, although the consideration of multiple objectives may seem a novel concept, virtually any nontrivial, real world problem invariably involves multiple objectives. For example, the success of an airplane is determined by such things as its cost (to be minimized), payload (to be maximized), speed (to be maximized), maximum range (to be maximized), weight (to be minimized), survivability (to be maximized) etc. And, in the design of an aircraft, we may actually hope to optimize each and every one of these parameters. The importance of multi-objective optimization can also be seen by the large number of applications presented in the literature as Agrell *et al.* (1998), Armann (1989), Eschenauer (1988), Ferreira and Machado (1996), Fu *et al.* (2000), Fu and Diwekar (2004), Johnson and Diwekar (2001), Kumar and Tewari (1991), Miettinen (1999), Ohkubo, Dissanayake and Taniwaki (1998). Most of these applications are multi-objective problems of nonlinear nature, which is why we need tools for nonlinear programming capable of handling multiple conflicting or incommensurable objectives.

2. Multivariate stratified sampling

We consider a multivariate population partitioned into L strata. Suppose that p characteristics are measured on each unit of the population. We assume that the strata boundaries are fixed in advance. Let n_i be the number of units drawn without replacement from i^{th} stratum ($i = 1, 2, \dots, L$). Let N_i be the size of i^{th} stratum. For j^{th} character, an unbiased estimate of the population mean \bar{Y}_j ($j = 1, 2, \dots, p$), denoted by \bar{y}_{jst} , has its sampling variance

$$V(\bar{y}_{jst}) = \sum_{i=1}^L \left(\frac{1}{n_i} - \frac{1}{N_i} \right) W_i^2 S_{ij}^2, \quad (j = 1, 2, \dots, p)$$

Where

$$W_i = \frac{N_i}{N}, \quad S_{ij}^2 = \frac{1}{N_i - 1} \sum_{h=1}^{N_i} (y_{ijh} - \bar{Y}_{ij})^2$$

Substituting $a_{ij} = W_i^2 S_{ij}^2$, we get

$$V(\bar{y}_{jst}) = \sum_{i=1}^L \frac{a_{ij}}{n_i} - \sum_{i=1}^L \frac{a_{ij}}{N_i}, \quad (j = 1, 2, \dots, p) \tag{1}$$

Let C_{ij} be the cost of enumerating the j^{th} character in the i^{th} stratum and let C be the upper limit on the total cost of the survey. Then assuming linear cost function, one should have

$$\sum_{i=1}^L \sum_{j=1}^p C_{ij} n_i \leq C \text{ or } \sum_{i=1}^L C_i n_i \leq C \tag{2}$$

Where $C_i = \sum_{j=1}^p C_{ij}$, the cost of enumeration of all the p characters in the i^{th} stratum.

Further one should have

$$1 \leq n_i \leq N_i, \quad (i = 1, 2, \dots, L) \tag{3}$$

We determine, the optimum values of n_i by minimizing (in some sense) all the p variances (equation 1) for a fixed budget (equation 2) i.e. we have to

$$\begin{aligned} \text{Minimize } V_j &= \sum_{i=1}^L \frac{a_{ij}}{n_i} - \sum_{i=1}^L \frac{a_{ij}}{N_i}, \quad (j = 1, 2, \dots, p) \\ \text{Subject to } &\sum_{i=1}^L C_i n_i \leq C \end{aligned} \tag{4}$$

and $1 \leq n_i \leq N_i, \quad (i = 1, 2, \dots, L)$

Since N_i 's are given, it is enough to minimize

$$V_j = \sum_{i=1}^L \frac{a_{ij}}{n_i}, \quad (j = 1, 2, \dots, p)$$

Using X_i for n_i , the problem (equation 4) can be written as the following multi-objective non-linear programming problem:

$$\left. \begin{aligned} \text{Minimize } V_j &= \sum_{i=1}^L \frac{a_{ij}}{X_i}, \quad (j = 1, 2, \dots, p) && (a) \\ \text{Subject to } &\sum_{i=1}^L C_i X_i \leq C && (b) \\ \text{and} &1 \leq X_i \leq N_i, \quad (i = 1, 2, \dots, L) && (c) \end{aligned} \right\} \tag{5}$$

The objective functions in (equation 5) are convex [see Kokan and Khan (1967)], the single constraint is linear and the bounds are also linear. The problem (5) is, therefore a multi-objective convex programming problem.

If some tolerance limits, say v_j are given on variances of the p characters then the allocation problem reduces to the single objective convex programming problem as:

$$\begin{aligned} \text{Minimize } &\sum_{i=1}^L C_i X_i \\ \text{Subject to } &\sum_{i=1}^L \frac{a_{ij}}{X_i} \leq v_j, \quad (j = 1, 2, \dots, p) \\ \text{and} &1 \leq X_i \leq N_i, \quad (i = 1, 2, \dots, L) \end{aligned} \tag{6}$$

3. Solution of a two dimensional multivariate problem when the cost is minimized

Let us consider the problem (equation 6). Due to its special character (only two dimension), we give in the following an easy method of solution by using the analytical approach of Kokan and Khan (1967). The problem is to

$$\begin{aligned}
 & \text{Minimize } C = \sum_{i=1}^2 C_i X_i \\
 & \text{Subject to } \sum_{i=1}^2 \frac{a_{ij}}{X_i} \leq v_j, \quad (j = 1, 2, \dots, p) \\
 & \text{and } 1 \leq X_i \leq N_i, \quad (i = 1, 2)
 \end{aligned} \tag{7}$$

Using the transformation $X_i = \frac{1}{x_i}$, this reduces to

$$\begin{aligned}
 & \text{Minimize } C = \sum_{i=1}^2 \frac{C_i}{x_i} \\
 & \text{Subject to } \sum_{i=1}^2 a_{ij} x_i \leq v_j, \quad (j = 1, 2, \dots, p) \\
 & \text{and } \frac{1}{N_i} \leq x_i \leq 1, \quad (i = 1, 2)
 \end{aligned} \tag{8}$$

4. Solution procedure

First we identify the linear constraints k_1 and k_2 such that

$$\left. \begin{aligned}
 \min_j \frac{v_j}{a_{1j}} &= \frac{v_{k1}}{a_{1k1}} \\
 \min_j \frac{v_j}{a_{2j}} &= \frac{v_{k2}}{a_{2k2}}
 \end{aligned} \right\} \tag{9}$$

Let us denote the minimum of C subject to the constraint (j) by $\underline{x}^{(j)}$. An explicit expression for $\underline{x}^{(j)} = (x_1^{(j)}, x_2^{(j)})$ is given by

$$x_i^{(j)} = \frac{v_j \sqrt{a_{ij} C_i}}{a_{ij} \left\{ \sum_{i=1}^2 \sqrt{a_{ij} C_i} \right\}}, \quad (i = 1, 2) \tag{10}$$

We illustrate the method by an (hypothetical) example represented in the following Figure 1 in which we have taken four constraints. The level curves of the objective functions touching the various constraints are also traced.

The minimum intercept on x_1 is cut by the constraint (1) and the minimum intercept on x_2 is cut by the constraint (4).

Now $\underline{x}^{(4)}$ violates the constraint (1) and $\underline{x}^{(1)}$ violates the constraint (4). A dangling solution, will then be the point of intersection of the lines (1) and (4), viz $\underline{x}^{(1,4)}$.

This new point however violates the constraint (2). So we test $\underline{x}^{(2)}$, which violates the constraint (1). Since $\underline{x}^{(1)}$ also violates the constraint (2), the intersection of the lines (1) and (2) is tested, which satisfies all the constraints and thus gives the optimal solution.

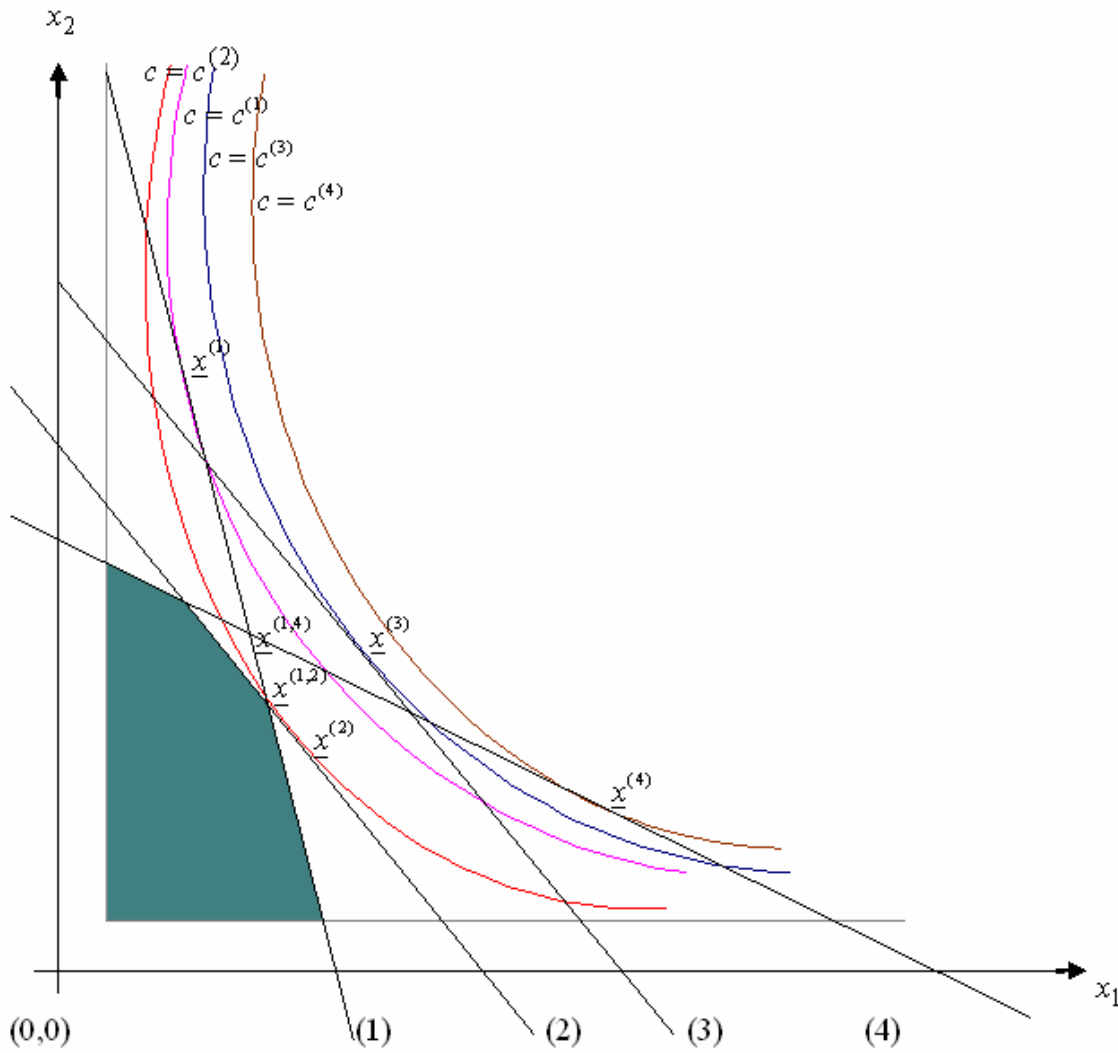


Figure 1. Graph for the hypothetical example

5. Numerical example

Let us consider the numerical example in which the upper bounds on three variances are given as 0.30, 0.60 and 0.50 respectively, divided into two strata with three characters under study for which the values of N_i , W_i , S_{i1} , S_{i2} , S_{i3} , C_{i1} , C_{i2} and C_{i3} are given in the following table:

Stratum (i)	N_i	W_i	S_{i1}	S_{i2}	S_{i3}	C_{i1}	C_{i2}	C_{i3}
1	180	0.40	1.5	2.25	0.75	0.6	0.9	1.5
2	270	0.60	3.0	4.75	5.25	0.8	1.2	2.0

The variance coefficients matrix is obtained by $a_{ij} = W_i^2 S_{ij}^2$ as

$$(a_{ij}) = \begin{pmatrix} 0.36 & 0.81 & 0.09 \\ 3.24 & 8.12 & 9.92 \end{pmatrix}$$

Let us fix the budget at 100 units.

Then the problem is to be solved is

$$\begin{aligned}
 & \text{Minimize } \frac{3}{x_1} + \frac{4}{x_2} \\
 & \text{Subject to } 0.36x_1 + 3.24x_2 \leq 0.30 \\
 & \quad 0.81x_1 + 8.12x_2 \leq 0.60 \\
 & \quad 0.09x_1 + 9.92x_2 \leq 0.50 \\
 & \quad 0.0056 \leq x_1 \leq 1 \\
 & \quad 0.0037 \leq x_2 \leq 1
 \end{aligned} \tag{11}$$

We identify the linear constraints (2) and (3) by using (9).

By using (9), we obtain $\underline{x}^{(2)}$ and $\underline{x}^{(3)}$ as (0.1591, 0.0580) and (0.4233, 0.0466).

Now, $\underline{x}^{(3)}$ violates the constraint (2) and $\underline{x}^{(2)}$ violates the constraint (3). Then the solution is $\underline{x}^{(2,3)} = (0.2585, 0.0481)$. This point also satisfies the constraint (1). Hence it is an optimal solution to the given problem.

The values of sample sizes n_1 and n_2 are found respectively as 3.87 and 20.79 which rounded to the nearest integers are 4 and 21. The value of the objective function at optimal point is 96.

6. Conclusions

The paper dealt with an important problem in multiobjective non linear programming for optimal allocation in stratified sampling, including various formulations of the problem, identifying the linear constraints, tracing the level curves of the objective functions touching the various constraints and then finding optimal solution which satisfies all the constraints. We considered non-linear cost function and continuous and integer sample size variables, graphical approach to easily understand the problem and later on illustrated by numerical example. Further studies may consider both the objective function and constraints as non-linear function and represent it graphically.

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