

Modified Variance Estimators in The Presence of Simultaneous Effects of Measurement Error and Non-Response Using Auxiliary Variable

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Abstract

The estimation of variance is crucial in recognizing the inherent diversity of natural items within any category. Survey sampling theories often assume that measurement error does not affect data collection observations, but in reality, deviations from true values lead to significant measurement errors, especially when respondents provide insufficient or no information – a situation known as nonresponse. This study investigates the simultaneous impact of measurement error and nonresponse on estimating finite population variance under simple random sampling (SRS) design, employing auxiliary variables. Proposed estimators for the study variable Y combine sample variance, ratio estimation, and exponential estimation based on various means. Through Taylor expansion, first-order mean square errors (MSEs) and approximate biases for the estimators are derived, and their efficiency is compared with existing methods. A numerical study is also conducted to confirm the efficacy of the proposed estimators.

Keywords; Non-response, Estimators, Measurement error, Efficiency

INTRODUCTION

Sampling is a critical aspect of research, influencing the accuracy of findings. Sampling theory aims to derive precise results about study variables through random samples. While assuming measurement errors don't impact observations during data collection, deviations from true values can lead to significant issues. Nonresponse occurs when respondents can't or won't provide enough information. The concept of modifying estimators using auxiliary information has been widely discussed by various authors, with Cochran (1940) and Kuk and Mak (1989) pioneering the use of auxiliary information for estimating population parameters. Many authors including Ahmed and Singh (2015), Audu *et al.* (2016a, b, c), Khalil *et al.* (2018,

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2019), Muili et al. (2018), Zahid and Shabbir (2019), Muili et al. (2019a), Muili et al. (2019b), Qureshi et al. (2019), Yadav et al. (2019), Sanaullah et al. (2020), Muil et al. (2020), Ishaq et al. (2020), Olayiwola et al. (2021), Yunusa et al. (2022) estimated the variance of population using auxiliary information.

Tariq et al. (2021) proposed variance estimators with auxiliary variables for measurement error under simple random sampling (SRS), drawing inspiration from Singh et al. (2011);

$$t_0 = \hat{s}_y^2 \quad (1.1)$$

$$t_1 = \hat{s}_y^2 \frac{S_x^2}{\hat{s}_x^2} \quad (1.2)$$

$$t_2 = \hat{s}_y^2 \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right) \quad (1.3)$$

$$t_1^{AM} = \frac{t_0 + t_1}{2} = \frac{\hat{s}_y^2}{2\left(1 + \frac{S_x^2}{\hat{s}_y^2}\right)} \quad (1.4)$$

$$t_1^{GM} = (t_0 t_1)^{1/2} = \hat{s}_y^2 \left(\frac{S_x^2}{\hat{s}_y^2}\right)^{1/2} \quad (1.5)$$

$$t_1^{AM} = \frac{2}{\left(\frac{1}{t_0} + \frac{1}{t_1}\right)} = \frac{2\hat{s}_y^2}{\left(1 + \frac{\hat{s}_y^2}{S_x^2}\right)} \quad (1.6)$$

$$MSE(t_1^{AM}) = MSE(t_1^{GM}) = MSE(t_1^{HM}) = \frac{S_y^4}{4n} (A_x - 4(A_y - (\delta - 1))) \quad (1.7)$$

$$t_2^{AM} = \frac{t_0 + t_2}{2} = \frac{\hat{s}_y^2}{2} \left(1 + \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right)\right) \quad (1.8)$$

$$t_2^{GM} = (t_0 t_2)^{1/2} = \hat{s}_y^2 \left(\exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right)\right)^{1/2} \quad (1.9)$$

$$t_2^{HM} = \frac{2}{\left(\frac{1}{t_0} + \frac{1}{t_2}\right)} = \frac{2\hat{s}_y^2}{\left(1 + \frac{1}{\exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right)}\right)}$$

(1.10)

$$MSE(t_2^{AM}) = MSE(t_2^{GM}) = MSE(t_2^{HM}) = \frac{S_y^4}{4n} \left(4A_y + \frac{A_x}{4} - 2(\delta - 1)\right)$$

(1.11)

$$t_3^{AM} = \frac{t_1 + t_2}{2} = \frac{\hat{s}_y^2}{2} \left(\frac{S_x^2}{\hat{s}_x^2} + \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right) \right)$$

(1.12)

$$t_3^{GM} = (t_1 t_2)^{1/2} = \hat{s}_y^2 \left(\frac{S_x^2}{\hat{s}_x^2} \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right) \right)^{1/2}$$

(1.13)

$$t_3^{HM} = \frac{2}{\left(\frac{1}{t_0} + \frac{1}{t_2}\right)} = \frac{2\hat{s}_y^2}{\left(\frac{S_x^2}{\hat{s}_x^2} + \frac{1}{\exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right)}\right)} \tag{1.14}$$

$$MSE(t_3^{AM}) = MSE(t_3^{GM}) = MSE(t_3^{HM}) = \frac{S_y^4}{4n} \left(4A_y + \frac{9A_x}{4} - 6(\delta - 1)\right) \tag{1.15}$$

$$t_4^{AM} = \frac{t_0 + t_1 + t_2}{3} = \frac{\hat{s}_y^2}{3} \left(1 + \frac{S_x^2}{\hat{s}_x^2} + \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right) \right)$$

(1.16)

$$t_4^{GM} = (t_0 t_1 t_2)^{1/2} = \hat{s}_y^2 \left(\frac{S_x^2}{\hat{s}_x^2} \exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right) \right)^{1/3}$$

(1.17)

$$t_4^{HM} = \frac{2}{\left(\frac{1}{t_0} + \frac{1}{t_1} + \frac{1}{t_2}\right)} = \frac{3\hat{s}_y^2}{\left(1 + \frac{1}{\frac{S_x^2}{\hat{s}_x^2} + \frac{1}{\exp\left(\frac{S_x^2 - \hat{s}_x^2}{S_x^2 + \hat{s}_x^2}\right)}}\right)} \tag{1.18}$$

$$MSE(t_{i5}^{AM}) = MSE(t_{i5}^{GM}) = MSE(t_{i5}^{HM}) = \frac{S_y^4}{n} \left(A_y + \frac{A_x}{4} - (\delta - 1) \right)$$

Finally, Tariq et al. (2021) suggest that their proposed estimators performed better than the

existing estimators when the data is characterized by measurement error.

MATERIALS AND METHODS

Proposed Estimators

Having studied the work of Tariq et al. (2021) the following estimators were proposed

$$T_1^{AM} = \frac{\hat{s}_y^{*2}}{2} \left(1 + \frac{S_x^2}{\hat{s}_x^{*2}} \right) \quad (2.1)$$

$$T_1^{GM} = \hat{s}_y^{*2} \left(\frac{S_x^2}{\hat{s}_x^{*2}} \right)^{1/2} \quad (2.2)$$

$$T_1^{HM} = \frac{2\hat{s}_y^{*2}}{\left(1 + 1 / \frac{S_x^2}{\hat{s}_x^{*2}} \right)} \quad (2.3)$$

$$T_2^{AM} = \frac{\hat{s}_y^{*2}}{2} \left(1 + \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right) \quad (2.4)$$

$$T_2^{GM} = \hat{s}_y^{*2} \left(\exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right)^{1/2} \quad (2.5)$$

$$T_3^{AM} = \frac{\hat{s}_y^{*2}}{2} \left(\frac{S_x^2}{\hat{s}_x^{*2}} + \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right) \quad (2.6)$$

$$T_2^{HM} = \frac{2\hat{s}_y^{*2}}{\left(1 + 1 / \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right)} \quad (2.7)$$

$$T_3^{GM} = \hat{s}_y^{*2} \left(\frac{S_x^2}{\hat{s}_x^{*2}} \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right)^{1/2} \quad (2.8)$$

$$T_3^{HM} = \frac{2\hat{s}_y^{*2}}{\left(1 / \frac{S_x^2}{\hat{s}_x^{*2}} + 1 / \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right)} \quad (2.9)$$

$$T_4^{AM} = \frac{\hat{s}_y^{*2}}{3} \left(1 + \frac{S_x^2}{\hat{s}_x^{*2}} + \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right) \quad (2.10)$$

$$T_4^{GM} = \hat{s}_y^{*2} \left(\frac{S_x^2}{\hat{s}_x^{*2}} \exp \left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}} \right) \right)^{1/3} \quad (2.11)$$

$$T_4^{HM} = \frac{3\hat{s}_y^{*2}}{\left(1 + 1/\frac{S_x^2}{\hat{s}_x^{*2}} + 1/\exp\left(\frac{S_x^2 - \hat{s}_x^{*2}}{S_x^2 + \hat{s}_x^{*2}}\right)\right)} \quad (2.12)$$

where

$$\hat{s}_y^{*2} = \frac{(n_1 - 1)\hat{s}_{y_1}^2 + n_2 \hat{s}_{y_{h_2}}^2}{n_1 + n_2 - 1} \quad \hat{s}_x^{*2} = \frac{(n_1 - 1)\hat{s}_{x_1}^2 + n_2 \hat{s}_{x_{h_2}}^2}{n_1 + n_2 - 1}$$

With the effect of measurement error for both respondents at the initial stage and respondents after call-back;

$$\begin{aligned} \hat{s}_{y_1}^2 &= s_{y_1}^2 - s_{u_1}^2, \hat{s}_{x_1}^2 = s_{x_1}^2 - s_{v_1}^2, \hat{s}_{y_{h_2}}^2 = s_{y_{h_2}}^2 - s_{u_2}^2, \hat{s}_{x_{h_2}}^2 = s_{x_{h_2}}^2 - s_{v_2}^2, s_{y_1}^2 = \frac{1}{n_1 - 1} \sum_{i=1}^{n_1} (y_i - \bar{y}_1)^2 \\ s_{x_1}^2 &= \frac{1}{n_1 - 1} \sum_{i=1}^{n_1} (x_i - \bar{x}_1)^2, s_{y_{h_2}}^2 = \frac{1}{n_2 - 1} \sum_{i=1}^{n_2} (y_i - \bar{y}_{h_2})^2, s_{x_{h_2}}^2 = \frac{1}{n_2 - 1} \sum_{i=1}^{n_2} (x_i - \bar{x}_{h_2})^2 \\ \bar{Y}_1 &= \frac{1}{N_1} \sum_{i=1}^{N_1} Y_i, \bar{Y}_{h_2} = \frac{1}{N_{h_2}} \sum_{i=1}^{N_{h_2}} Y_{hi}, \bar{y}_1 = \frac{1}{n_1} \sum_{i=1}^{n_1} y_i, \bar{y}_{h_2} = \frac{1}{h_2} \sum_{i=1}^{h_2} y_{hi} \end{aligned}$$

Biases and Mean Squared Errors (MSEs) of the Proposed Estimators

To obtain the properties of T_i^{AM}, T_i^{GM} and T_i^{HM} ($i=1,2,3$) which are Biases and MSEs the following error terms are defined.

$$e_0 = \frac{\hat{s}_y^{*2} - S_y^2}{S_y^2}, e_1 = \frac{\hat{s}_x^{*2} - S_x^2}{S_x^2}, \text{ such that } \hat{s}_y^{*2} = S_y^2(1 + e_0), \hat{s}_x^{*2} = S_x^2(1 + e_1) \text{ respectively.}$$

The expectation of error terms was obtained as;

$$\left. \begin{aligned} E(e_0) &= E(e_1) = 0, \\ E(e_0^2) &= k_1 \left[\gamma_{2y} + \gamma_u \frac{S_u^4}{S_y^4} + 2 \left(1 + \frac{S_u^4}{S_y^4} \right)^2 \right] + k_2 \left[\gamma_{2y_2} + \gamma_{u_2} \frac{S_{u_2}^4}{S_{y_2}^4} + 2 \left(1 + \frac{S_{u_2}^4}{S_{y_2}^4} \right)^2 \right], \\ E(e_1^2) &= k_1 \left[\gamma_{2x} + \gamma_v \frac{S_v^4}{S_x^4} + 2 \left(1 + \frac{S_v^4}{S_x^4} \right)^2 \right] + k_2 \left[\gamma_{2x_2} + \gamma_{v_2} \frac{S_{v_2}^4}{S_{x_2}^4} + 2 \left(1 + \frac{S_{v_2}^4}{S_{x_2}^4} \right)^2 \right], \\ E(e_0 e_1) &= k_1 \left[\frac{\mu_{22}(X, Y)}{S_x^2 S_y^2} \right] + k_2 \left[\frac{\mu_{22}(X, Y)_2}{S_{x_2}^2 S_{y_2}^2} \right] \end{aligned} \right\} \quad (2.13)$$

Let;

$$A = k_1 \left[\gamma_{2y} + \gamma_u \frac{S_u^4}{S_y^4} + 2 \left(1 + \frac{S_u^4}{S_y^4} \right)^2 \right] + k_2 \left[\gamma_{2y_2} + \gamma_{u_2} \frac{S_{u_2}^4}{S_{y_2}^4} + 2 \left(1 + \frac{S_{u_2}^4}{S_{y_2}^4} \right)^2 \right], \quad (2.14)$$

$$B = k_1 \left[\gamma_{2x} + \gamma_v \frac{S_v^4}{S_x^4} + 2 \left(1 + \frac{S_v^4}{S_x^4} \right)^2 \right] + k_2 \left[\gamma_{2x_2} + \gamma_{v_2} \frac{S_{v_2}^4}{S_{x_2}^4} + 2 \left(1 + \frac{S_{v_2}^4}{S_{x_2}^4} \right)^2 \right], \quad (2.15)$$

$$C = k_1 \frac{\mu_{22}(X, Y)}{S_x^2 S_y^2} + k_2 \frac{\mu_{22}(X, Y)_2}{S_{x_2}^2 S_{y_2}^2} \quad (2.16)$$

where

$$k_1 = \frac{1}{n} - \frac{1}{N}, \quad k_2 = \frac{N_2(k-1)}{Nn} = \frac{N_2 \left(\frac{n_2-1}{h_2} \right)}{Nn} \quad \text{and } k = \frac{n_2}{h_2}$$

Expressing the proposed estimators T_1^{AM} , T_1^{GM} , T_1^{HM} in term of error terms, the following are obtained.

$$T_1^{AM} = \frac{S_y^2(1+e_0)}{2} (2 + -e_1 + e_1^2) = S_y^2 \left(1 - \frac{e_1}{2} + \frac{e_1^2}{2} + e_0 - e_0 e_1 \right) \quad (2.17)$$

$$T_1^{GM} = S_y^2(1+e_0) \left(1 - \frac{1}{2}e_1 + \frac{3}{8}e_1^2 \right) = S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{3}{8}e_1^2 + e_0 + e_0 e_1 \right) \quad (2.18)$$

$$T_1^{HM} = S_y^2(1+e_0) \left(1 - \frac{1}{2}e_1 + \frac{1}{4}e_1^2 \right) = S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{1}{4}e_1^2 + e_0 - \frac{1}{2}e_0 e_1 \right) \quad (2.19)$$

By subtracting S_y^2 from (2.16), (2.17) and (2.18), and taking the expectation we have;

$$\begin{aligned} Bias(T_1^{AM}) &= \frac{S_y^2}{2} (2E(e_0) - E(e_1) + E(e_1^2) - E(e_0 e_1)) \\ Bias(T_1^{AM}) &= \frac{S_y^2}{2} \{ B - C \} \end{aligned} \quad (2.20)$$

$$\begin{aligned} Bias(T_1^{GM}) &= \frac{S_y^2}{8} (8E(e_0) - 4E(e_1) + 3E(e_1^2) - 4E(e_0 e_1)) \\ Bias(T_1^{GM}) &= \frac{S_y^2}{8} \{ B - 4C \} \end{aligned} \quad (2.21)$$

$$\begin{aligned} Bias(T_1^{HM}) &= \frac{S_y^2}{4} (4E(e_0) - 2E(e_1) + E(e_1^2) - 2E(e_0 e_1)) \\ Bias(T_1^{HM}) &= \frac{S_y^2}{4} \{ B - 2C \} \end{aligned} \quad (2.22)$$

By subtracting S_y^2 from (2.17), (2.18) and (2.19), and square it to first order approximation then take the expectation we obtained;

$$\begin{aligned} MSE(T_1^{AM}) &= E \left(S_y^2 \left(1 - \frac{e_1}{2} + \frac{e_1^2}{2} + e_0 - e_0 e_1 \right) - S_y^2 \right)^2 \\ MSE(T_1^{AM}) &= \frac{S_y^4}{4} \{ B + 4(A - C) \} \end{aligned} \quad (2.23)$$

$$\begin{aligned} MSE(T_1^{GM}) &= E \left(S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{3}{8}e_1^2 + e_0 + e_0 e_1 \right) - S_y^2 \right)^2 \\ MSE(T_1^{GM}) &= \frac{S_y^4}{4} \{ B + 4(A - C) \} \end{aligned} \quad (2.24)$$

$$MSE(T_1^{HM}) = E\left(S_y^2\left(1 - \frac{1}{2}e_1 + \frac{1}{4}e_1^2 + e_0 - \frac{1}{2}e_0e_1\right) - S_y^2\right)^2$$

$$MSE(T_1^{HM}) = \frac{S_y^4}{4}\{B + 4(A - C)\} \quad (2.25)$$

This implies that $MSE(T_1^{AM}) = MSE(T_1^{GM}) = MSE(T_1^{HM})$

Also, by expressing T_2^{AM} , T_2^{GM} and T_2^{HM} in terms of e_0 and e_1 ;

$$T_2^{AM} = \frac{S_y^2(1+e_0)}{2} \left(1 + \exp\left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)}\right)\right) = \frac{S_y^2(1+e_0)}{2} \left(1 + \exp\left(\frac{-e_1}{2+e_1}\right)\right) \quad (2.26)$$

$$T_2^{GM} = S_y^2(1+e_0) \left(1 + \exp\left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)}\right)\right)^{\frac{1}{2}} = S_y^2 \left(1 - \frac{1}{4}e_1 + \frac{5}{32}e_1^2 + e_0 - \frac{1}{4}e_0e_1\right) \quad (2.27)$$

$$T_2^{HM} = \frac{2S_y^2(1+e_0)}{\left(1 + \exp\left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)}\right)\right)} = S_y^2 \left(1 - \frac{1}{4}e_1 + \frac{3}{16}e_1^2 + e_0 - \frac{1}{4}e_0e_1\right) \quad (2.28)$$

By subtracting S_y^2 from (2.26), (2.27) and (2.28), and taking the expectation we have;

$$Bias(T_2^{AM}) = \frac{S_y^2}{16}\{B - 8C\} \quad (2.29)$$

$$Bias(T_2^{GM}) = \frac{S_y^2}{4}\left\{\frac{5}{8}B - C\right\} \quad (2.30)$$

$$Bias(T_2^{HM}) = \frac{S_y^2}{4}\left\{\frac{3}{4}B - C\right\} \quad (2.31)$$

Also, by subtracting S_y^2 from (2.26), (2.27) and (2.28), and squaring it to first order approximation then take the expectation we obtained;

$$MSE(T_2^{AM}) = \frac{S_y^4}{4}\left\{4A + \frac{1}{4}B - 2C\right\} \quad (2.32)$$

$$MSE(T_2^{GM}) = \frac{S_y^4}{4}\left\{4A + \frac{1}{4}B - 2C\right\} \quad (2.33)$$

$$MSE(T_2^{HM}) = \frac{S_y^4}{4}\left\{4A + \frac{1}{4}B - 2C\right\} \quad (2.34)$$

This also implies that $MSE(T_2^{AM}) = MSE(T_2^{GM}) = MSE(T_2^{HM})$.

Also, by expressing T_3^{AM} , T_3^{GM} and T_3^{HM} in terms of e_0 and e_1 ;

$$T_3^{AM} = \frac{S_y^2(1+e_0)}{2} \left(\frac{S_x^2}{S_x^2(1+e_1)} + \exp\left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)}\right)\right) = S_y^2 \left(1 - \frac{3}{4}e_1 + \frac{11}{16}e_1^2 + e_0 - \frac{3}{4}e_0e_1\right) \quad (2.35)$$

$$T_3^{GM} = S_y^2(1+e_0) \left(\frac{S_y^2}{S_x^2(1+e_1)} \exp \left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)} \right) \right)^{1/2} = S_y^2 \left(1 - \frac{3}{4}e_1 + \frac{21}{32}e_1^2 + e_0 - \frac{3}{4}e_0e_1 \right) \quad (2.36)$$

$$T_3^{HM} = \frac{2S_y^2(1+e_0)}{\left(1 / \left(\frac{S_x^2}{S_x^2(1+e_1)} \right) + 1 / \exp \left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)} \right) \right)} = S_y^2 \left(1 - \frac{3}{4}e_1 + \frac{5}{8}e_1^2 + e_0 - \frac{3}{4}e_1 \right) \quad (2.37)$$

By subtracting S_y^2 from (2.35), (2.36) and (2.37), and taking the expectation we have;

$$Bias(T_3^{AM}) = \frac{S_y^2}{8} \left(\frac{11}{2}B - 6C \right) \quad (2.38)$$

$$Bias(T_3^{GM}) = \frac{S_y^2}{4} \left\{ \frac{21}{8}B - 3C \right\} \quad (2.39)$$

$$Bias(T_3^{HM}) = \frac{S_y^2}{4} \left\{ \frac{5}{2}B - 3C \right\} \quad (2.40)$$

Also, by subtracting S_y^2 from (2.35), (2.36) and (2.37), and squaring it to first order approximation then take the expectation we obtained;

$$MSE(T_3^{AM}) = \frac{S_y^4}{4} \left\{ 4A + \frac{9}{4}B - 6C \right\} \quad (2.41)$$

$$MSE(T_3^{GM}) = \frac{S_y^4}{4} \left\{ 4A + \frac{9}{4}B - 6C \right\} \quad (2.42)$$

$$MSE(T_3^{HM}) = \frac{S_y^4}{4} \left\{ 4A + \frac{9}{4}B - 6C \right\} \quad (2.43)$$

This also implies that $MSE(T_3^{AM}) = MSE(T_3^{GM}) = MSE(T_3^{HM})$

Also, by expressing T_3^{AM} , T_3^{GM} and T_3^{HM} in terms of e_0 and e_1 ;

$$T_4^{AM} = \frac{S_y^2(1+e_0)}{3} \left(1 + \frac{S_x^2}{S_x^2(1+e_1)} + \exp \left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)} \right) \right) = S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{11}{24}e_1^2 + e_0 - \frac{1}{2}e_0e_1 \right) \quad (2.44)$$

$$T_4^{GM} = S_y^2(1+e_0) \left(\frac{S_x^2}{S_x^2(1+e_1)} \exp \left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)} \right) \right)^{1/3} = S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{3}{8}e_1^2 + e_0 - \frac{1}{2}e_0e_1 \right) \quad (2.45)$$

$$T_4^{HM} = \frac{3S_y^2(1+e_0)}{\left(1 + 1 / \left(\frac{S_x^2}{S_x^2(1+e_1)} \right) + 1 / \exp \left(\frac{S_x^2 - S_x^2(1+e_1)}{S_x^2 + S_x^2(1+e_1)} \right) \right)} = S_y^2 \left(1 - \frac{1}{2}e_1 + \frac{7}{24}e_1^2 + e_0 - \frac{1}{2}e_0e_1 \right) \quad (2.46)$$

By subtracting S_y^2 from (2.44), (2.45) and (2.46), and taking the expectation we have;

$$Bias(T_4^{AM}) = \frac{S_y^2}{2} \left\{ \frac{11}{12}B - C \right\} \quad (2.47)$$

$$Bias(T_4^{GM}) = \frac{1}{2} S_y^2 \left\{ \frac{3}{4} B - C \right\} \quad (2.48)$$

$$Bias(T_4^{HM}) = \frac{S_y^2}{2} \left\{ \frac{7}{12} B - C \right\} \quad (2.49)$$

Also, by subtracting S_y^2 from (2.44), (2.45) and (2.46), and squaring it to first order approximation then take the expectation we obtained;

$$MSE(T_4^{AM}) = S_y^4 \left\{ A + \frac{1}{4} B - C \right\} \quad (2.50)$$

$$MSE(T_4^{GM}) = S_y^4 \left\{ A + \frac{1}{4} B - C \right\} \quad (2.51)$$

$$MSE(T_4^{HM}) = S_y^4 \left\{ A + \frac{1}{4} B - C \right\} \quad (2.52)$$

This also implies that $MSE(T_4^{AM}) = MSE(T_4^{GM}) = MSE(T_4^{HM})$

Efficiency Comparison

In this section, the efficiency conditions of the proposed estimators over some existing estimators considered in this study were established.

Comparing sample, ratio, and exponential variance estimators with proposed estimators;

$MSE(t_{i\bullet})$, $i\bullet=0,1,2$. with $MSE(T_i^J)$, where $J = AM, GM, HM$ and $i=1,2,3,4$

$$MSE(T_1^J) - MSE(t_0) < 0$$

$$S_y^4 \{ A + B - 2C \} - S_y^4 A < 0 \quad \text{if } B < 4C \quad (3.1)$$

$$MSE(T_2^J) - MSE(t_0) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4} B - 2C \right\} - S_y^4 A < 0 \quad \text{if } B < 8C \quad (3.2)$$

$$MSE(T_3^J) - MSE(t_0) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4} B - 2C \right\} - S_y^4 A < 0 \quad \text{if } B < \frac{8}{3} C \quad (3.3)$$

$$MSE(T_4^J) - MSE(t_0) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4} B - 2C \right\} - S_y^4 A < 0 \quad \text{if } B < 4C \quad (3.4)$$

$$MSE(T_1^J) - MSE(t_1) < 0$$

$$S_y^4 \{ A + B - 2C \} - S_y^4 \{ A + B - 2C \} < 0 \quad \text{if } B > \frac{4}{3} C \quad (3.5)$$

$$MSE(T_2^J) - MSE(t_1) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4} B - 2C \right\} - S_y^4 \{ A + B - 2C \} < 0 \quad \text{if } B > \frac{8}{5} C \quad (3.6)$$

$$MSE(T_3^J) - MSE(t_1) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4}B - 2C \right\} - S_y^4 \{A + B - 2C\} < 0 \quad \text{if } B > \frac{8}{7}C \quad (3.7)$$

$$MSE(T_4^J) - MSE(t_1) < 0$$

$$\frac{S_y^4}{4} \left\{ 4A + \frac{1}{4}B - 2C \right\} - S_y^4 \{A + B - 2C\} < 0 \quad \text{if } B > \frac{4}{3}C \quad (3.8)$$

$$MSE(T_1^J) - MSE(t_2) < 0$$

$$S_y^4 \{A + B - 2C\} - \frac{S_y^4}{4} \{B + 4(A - C)\} < 0 \quad \text{if } B > \frac{8}{3}C \quad (3.9)$$

Empirical Study

In this section, empirical studies were conducted to assess the performance of proposed estimators over some existing estimators mentioned in the literature. The data was simulated using R Software by generating different samples of size 50, 100, and 200 were selected using simple random sampling without replacement from the population of size $N = 1,000$.

Table 1: Population Used for Simulation Study

| Auxiliary variable | Study variable |
|---|---|
| $z_1 \sim \text{Beta}(1, 3), z_2 \sim \text{Gamma}(5, 7)$ $X = z_1 \rho_{z_1 z_2} + z_2 \sqrt{1 - \rho_{z_1 z_2}^2}$ | $Y = 0.2X + 0.5X^2 + e$ $e \sim N(0, 1)$ |

RESULTS AND DISCUSSION

Table 2: Biases, MSEs and PREs of Proposed and Existing Estimators for $n = 50$.

| | $n = 50,$ | $n_1 = 40,$ | $n_2 = 10,$ | $h_2 = 8$ |
|----------------------------|-------------------|-------------|-------------|-------------|
| Existing Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 3.50727167 | 13.45363145 | 100.00000 |
| | Ratio t_1 | -0.39133991 | 0.15367127 | 8754.81266 |
| | Exponential t_2 | 1.05007510 | 1.26445052 | 1063.99035 |
| Proposed Estimators | T_1^{AM} | 3.54202247 | 13.70891038 | 98.13786 |
| | T_1^{GM} | 0.05777009 | 0.02034883 | 66114.99766 |
| | T_1^{HM} | -0.32448606 | 0.10725141 | 12544.01322 |
| | T_2^{AM} | 2.27867338 | 5.73673820 | 234.51709 |
| | T_2^{GM} | 1.98768842 | 4.38263133 | 306.97612 |
| | T_2^{HM} | 1.72762492 | 3.32710828 | 404.36410 |
| | T_3^{AM} | 0.32936759 | 0.15112749 | 8902.17383 |
| | T_3^{GM} | -0.14054664 | 0.02630606 | 51142.71704 |

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| | | | | |
|--|-------------------|-------------|-------------|-------------|
| | T_3^{HM} | -0.32851267 | 0.10969460 | 12264.62462 |
| | T_4^{AM} | 1.38866895 | 2.17358888 | 618.95934 |
| | T_4^{GM} | 0.27811869 | 0.11059486 | 12164.78860 |
| | T_4^{HM} | -0.26591462 | 0.07446513 | 18067.02186 |
| $n = 50, \quad n_1 = 30, \quad n_2 = 20, \quad h_2 = 15$ | | | | |
| Existing Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 2.63413328 | 7.89121270 | 100.00000 |
| | Ratio t_1 | -0.42552306 | 0.18123845 | 4354.04999 |
| | Exponential t_2 | 0.70372046 | 0.62821997 | 1256.12256 |
| Proposed Estimators | T_1^{AM} | 2.65179251 | 7.99197448 | 98.73921 |
| | T_1^{GM} | -0.13385340 | 0.02767950 | 28509.23013 |
| | T_1^{HM} | -0.39107774 | 0.15358992 | 5137.84549 |
| | T_2^{AM} | 1.66892687 | 3.23463038 | 243.96026 |
| | T_2^{GM} | 1.43764371 | 2.42271419 | 325.71785 |
| | T_2^{HM} | 1.23148103 | 1.79845662 | 438.77693 |
| | T_3^{AM} | 0.13909870 | 0.05405839 | 14597.57274 |
| | T_3^{GM} | -0.26016005 | 0.07137759 | 11055.58902 |
| | T_3^{HM} | -0.39246389 | 0.15463715 | 5103.05102 |
| | T_4^{AM} | 0.97077689 | 1.14439053 | 689.55593 |
| | T_4^{GM} | 0.03743289 | 0.02344332 | 33660.82243 |
| | T_4^{HM} | -0.35949510 | 0.13055761 | 6044.23822 |

Table 3: Biases, MSEs and PREs of Proposed and Existing Estimators for $n = 100$.

| | | | | |
|---|-------------------|-------------|-------------|--------------|
| $n = 100, \quad n_1 = 80, \quad n_2 = 20, \quad h_2 = 15$ | | | | |
| Existing Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 3.46775198 | 12.60875815 | 100.00000 |
| | Ratio t_1 | -0.39358503 | 0.15514205 | 8127.23464 |
| | Exponential t_2 | 1.03388633 | 1.15094178 | 1095.51659 |
| Proposed Estimators | T_1^{AM} | 3.50138022 | 12.84859331 | 98.13337 |
| | T_1^{GM} | 0.05017056 | 0.01102441 | 114371.31066 |
| | T_1^{HM} | -0.32870024 | 0.10892320 | 11575.82445 |
| | T_2^{AM} | 2.25081915 | 5.34186920 | 236.03644 |
| | T_2^{GM} | 1.96239991 | 4.06971955 | 309.81885 |
| | T_2^{HM} | 1.70466353 | 3.07939993 | 409.45504 |
| | T_3^{AM} | 0.32015065 | 0.12414197 | 10156.72502 |
| | T_3^{GM} | -0.14551274 | 0.02443606 | 51598.98731 |
| T_3^{HM} | -0.33236173 | 0.11126992 | 11331.68646 | |

Modified Variance Estimators in The Presence of Simultaneous Effects of Measurement Error and Non-Response Using Auxiliary Variable

| | | | | |
|---|-------------------|-------------|-------------|-------------|
| | T_4^{AM} | 1.36935109 | 1.99935854 | 630.64017 |
| | T_4^{GM} | 0.26915385 | 0.08933189 | 14114.51005 |
| | T_4^{HM} | -0.27135662 | 0.07535302 | 16732.91741 |
| $n = 100,$ $n_1 = 60,$ $n_2 = 40,$ $h_2 = 30$ | | | | |
| Existing Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 2.64721033 | 7.49206269 | 100.00000 |
| | Ratio t_1 | -0.42647650 | 0.18194787 | 4117.69728 |
| Proposed Estimators | Exponential t_2 | 0.70783008 | 0.56851435 | 1317.83176 |
| | T_1^{AM} | 2.66439283 | 7.58686862 | 98.75039 |
| | T_1^{GM} | -0.13555344 | 0.02289350 | 32725.71382 |
| | T_1^{HM} | -0.39289218 | 0.15461838 | 4845.51871 |
| | T_2^{AM} | 1.67752020 | 3.04241719 | 246.25363 |
| | T_2^{GM} | 1.44501134 | 2.26884534 | 330.21478 |
| | T_2^{HM} | 1.23778529 | 1.67525249 | 447.21991 |
| | T_3^{AM} | 0.14067679 | 0.03735126 | 20058.39398 |
| | T_3^{GM} | -0.26133382 | 0.06999776 | 10703.28951 |
| | T_3^{HM} | -0.39414438 | 0.15559088 | 4815.23269 |
| | T_4^{AM} | 0.97618797 | 1.05551769 | 709.79982 |
| | T_4^{GM} | 0.03689994 | 0.01200851 | 62389.59509 |
| | T_4^{HM} | -0.36189641 | 0.13149468 | 5697.61652 |

Table 4: Biases, MSEs and PREs of Proposed and Existing Estimators for $n = 200$.

| | | | | |
|--|-------------------|--------------|--------------|--------------|
| $n = 200,$ $n_1 = 150,$ $n_2 = 50,$ $h_2 = 38$ | | | | |
| Existing Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 3.336806616 | 11.409953567 | 100.00000 |
| | Ratio t_1 | -0.405038318 | 0.164132168 | 6951.68638 |
| | Exponential t_2 | 0.977289739 | 0.993651203 | 1148.28559 |
| Proposed Estimators | T_1^{AM} | 3.364708214 | 11.599183607 | 98.36859 |
| | T_1^{GM} | -0.001755572 | 0.003392118 | 336366.66081 |
| | T_1^{HM} | -0.350887023 | 0.123412032 | 9245.41421 |
| | T_2^{AM} | 2.157048178 | 4.782941934 | 238.55513 |
| | T_2^{GM} | 1.876141835 | 3.622988091 | 314.93213 |
| | T_2^{HM} | 1.625379427 | 2.723544561 | 418.93765 |
| | T_3^{AM} | 0.286125710 | 0.091963773 | 12407.00897 |
| | T_3^{GM} | -0.178285760 | 0.033076029 | 34496.14059 |
| | T_3^{HM} | -0.353486392 | 0.125222204 | 9111.76552 |
| T_4^{AM} | 1.303019346 | 1.756373181 | 649.63151 | |

Modified Variance Estimators in The Presence of Simultaneous Effects of Measurement Error and Non-Response Using Auxiliary Variable

| | | | | |
|----------------------------|-------------------|--------------|-------------|-------------|
| | T_4^{GM} | 0.210530177 | 0.051465279 | 22170.19673 |
| | T_4^{HM} | -0.302099003 | 0.091843817 | 12423.21360 |
| $n = 200,$ | $n_1 = 130,$ | $n_2 = 70,$ | $h_2 = 53$ | |
| Exiting Estimators | Estimators | Bias | MSEs | PREs |
| | Sample t_0 | 2.92623586 | 8.80993643 | 100.00000 |
| | Ratio t_1 | -0.42062531 | 0.17696421 | 4978.37197 |
| Proposed Estimators | Exponential t_2 | 0.81478259 | 0.69833004 | 1261.57202 |
| | T_1^{AM} | 2.94634396 | 8.92987944 | 98.65684 |
| | T_1^{GM} | -0.09259045 | 0.01102648 | 79898.00402 |
| | T_1^{HM} | -0.38136972 | 0.14559183 | 6051.12025 |
| | T_2^{AM} | 1.87050923 | 3.61531695 | 243.68365 |
| | T_2^{GM} | 1.61777027 | 2.70944587 | 325.15639 |
| | T_2^{HM} | 1.39243138 | 2.01193173 | 437.88446 |
| | T_3^{AM} | 0.19707864 | 0.04781838 | 18423.74547 |
| | T_3^{GM} | -0.23482628 | 0.05606907 | 15712.64915 |
| | T_3^{HM} | -0.38290744 | 0.14675909 | 6002.99214 |
| | T_4^{AM} | 1.10679771 | 1.27735638 | 689.70074 |
| | T_4^{GM} | 0.09609941 | 0.01488222 | 59197.73827 |
| | T_4^{HM} | -0.34529224 | 0.11953367 | 7370.25506 |

The outcomes presented in the tables demonstrate that the suggested estimators exhibit lower Mean Squared Errors (MSEs) and higher Percentage Relative Efficiencies (PREs), surpassing the performance of existing estimators. This superiority is particularly evident when dealing with data affected by both measurement error and nonresponse concurrently. Estimators with minimal MSEs and maximal PREs are deemed more potent and efficient compared to their counterparts.

CONCLUSION

In this paper, the problem of estimation of finite population variance in the presence of measurement error and nonresponse was considered simultaneously. The estimators proposed were a combination of the mean of sample variance estimator, ratio and exponential variance estimators arithmetically, geometrically and harmonically by following Tarq et al. (2021) under SRS design. The efficiency conditions are also obtained in which the proposed estimators may perform better than the existing estimators. The results obtained for MSEs and PREs of the simulation study show that the proposed estimators performed better than other estimators available in the literature when the population is characterized with measurement error and nonresponse simultaneously. The PREs of the suggested estimators increase and the ARBs decrease by increases in the sample sizes. Based on the numerical findings, we recommend the proposed estimators for the estimation of population variance.

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